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OSL2022



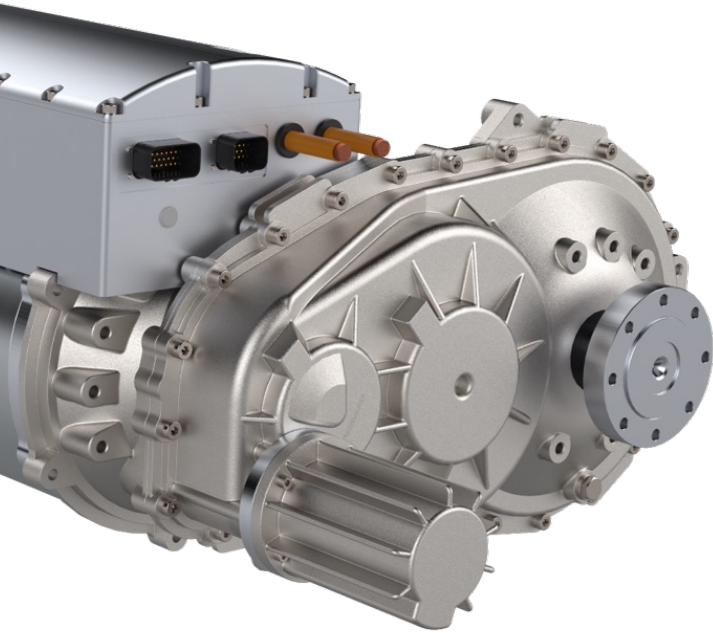
## **Top-down Validation Framework for Efficient and Low Noise Electric Driven Vehicles with Shiftable Gearbox**

Steffen Jäger, Jonas Schätzle, Tilmann Linde

Furtwangen University, Germany

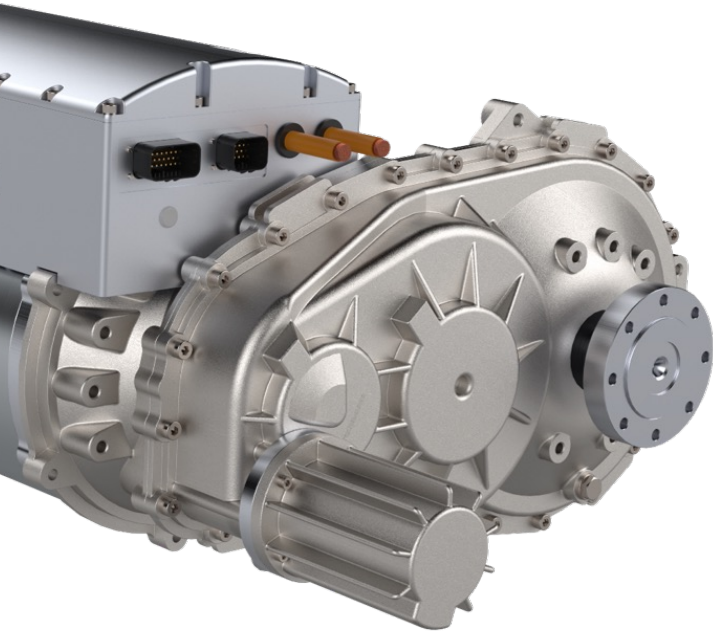
14.06.2022

- Introduction
- Top-down Validation Framework
- Model Implementation
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- Physical Validation Environment
- Conclusion and Outlook



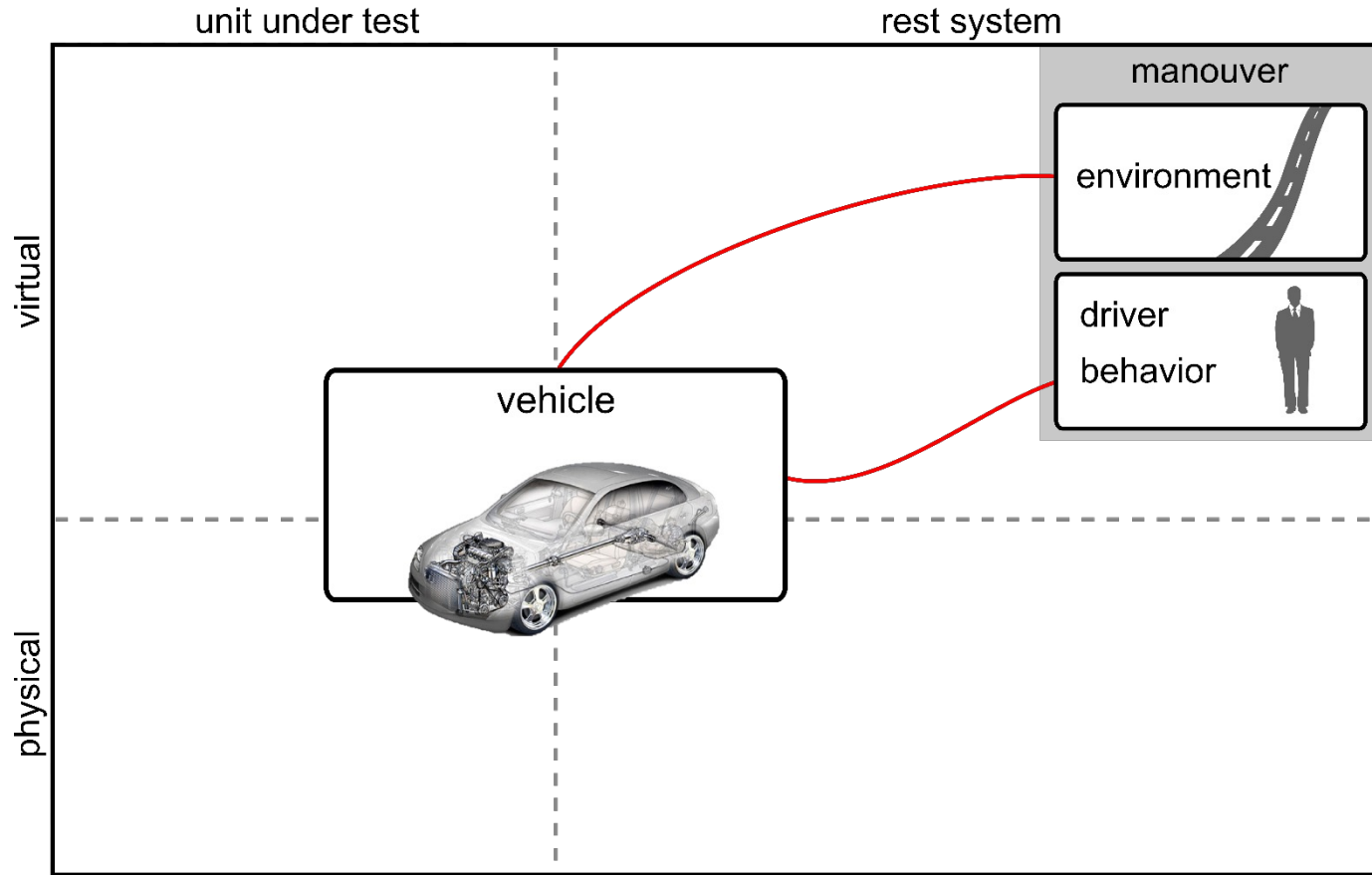
# Introduction

- **Project:** Efficient and Low Noise Electric Powertrain Systems
- **Motivation**
  - Using a shiftable gearbox to improve the efficiency of an electric drive system
  - Optimization of an existing powertrain system regarding to efficiency and sound emission
  - Supporting (smaller) automotive suppliers in the technological transformation by providing modern product development methods and process models
- **Approach**
  - Using top-down validation strategies to come to a real/virtual coupled XiL framework with different layers of validated (sub)models



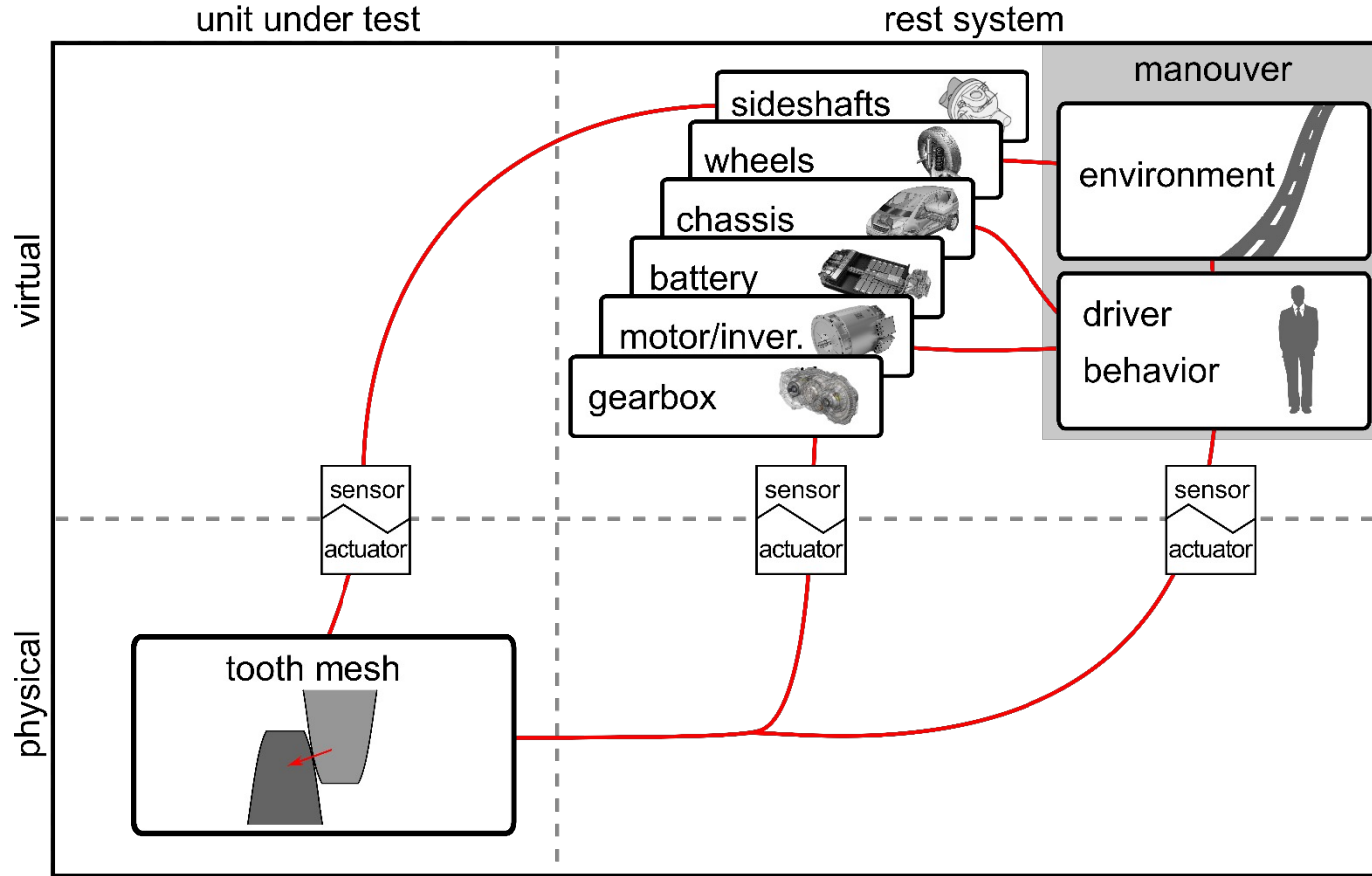
# Top-down Validation Framework

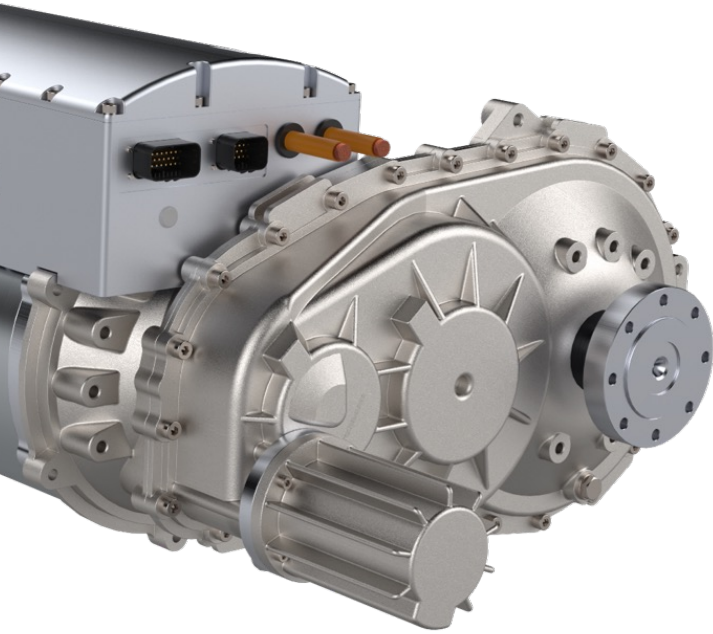
# Top-down Validation Framework



Quelle: Albers, Geier, Jäger [Albers13]

# Top-down Validation Framework



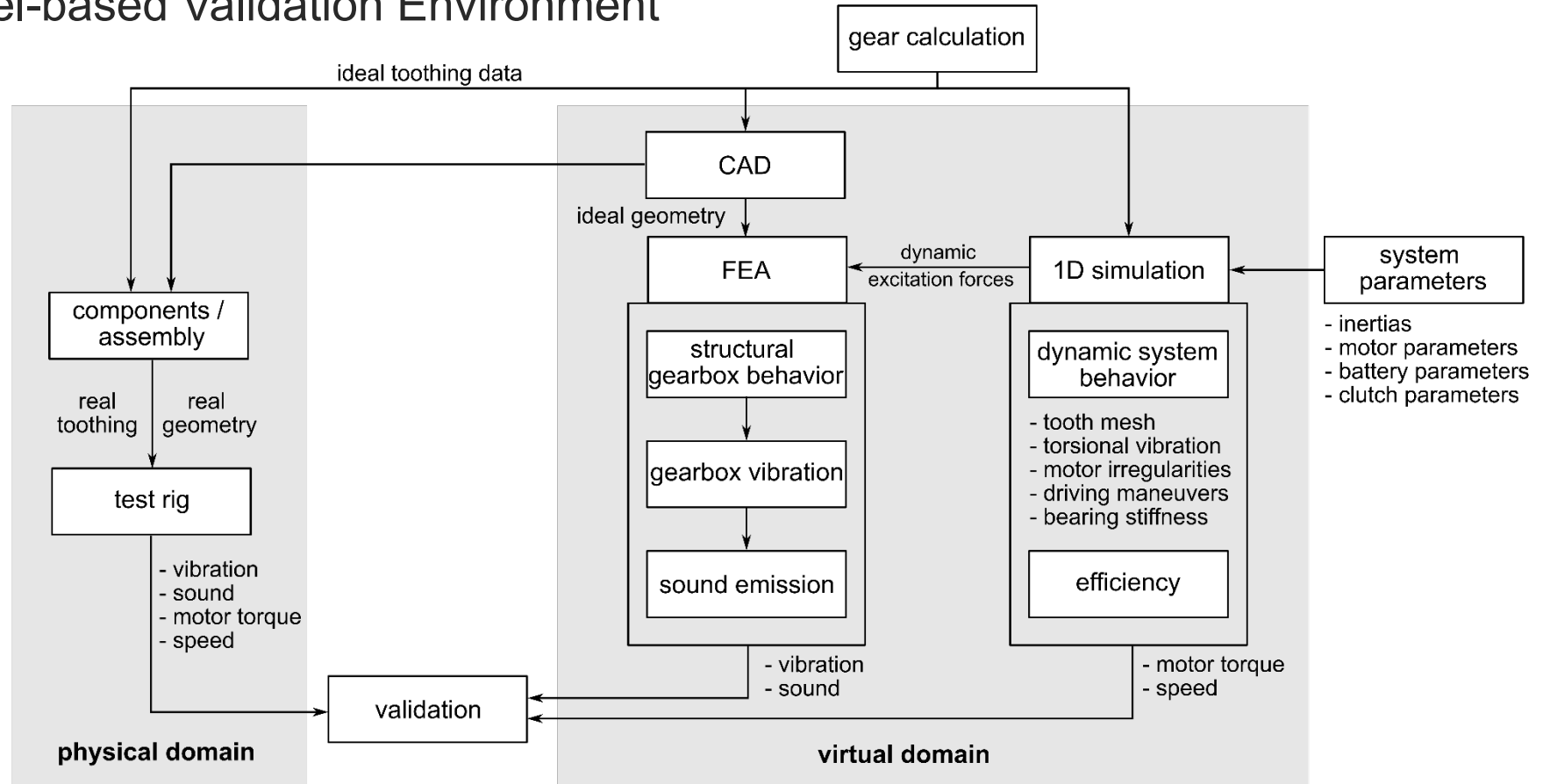


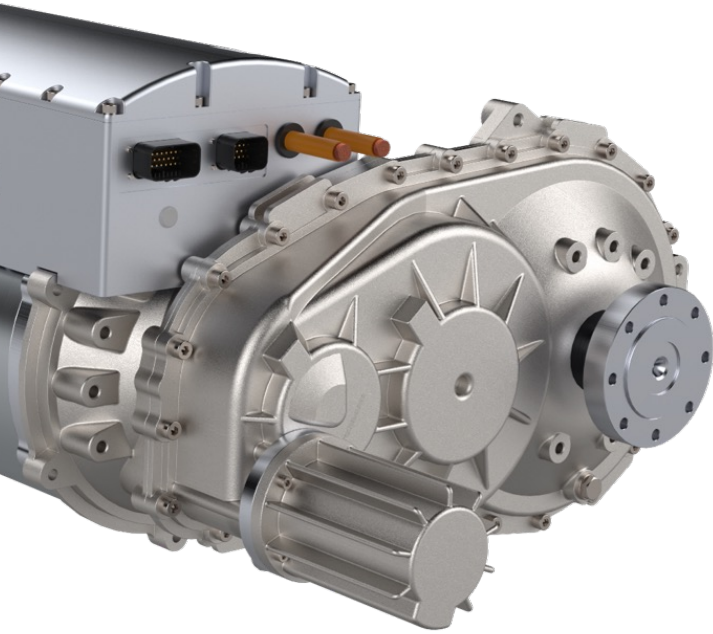
# Model Implementation

Tooth Mesh Layer – Model Overview



## ■ Model-based Validation Environment



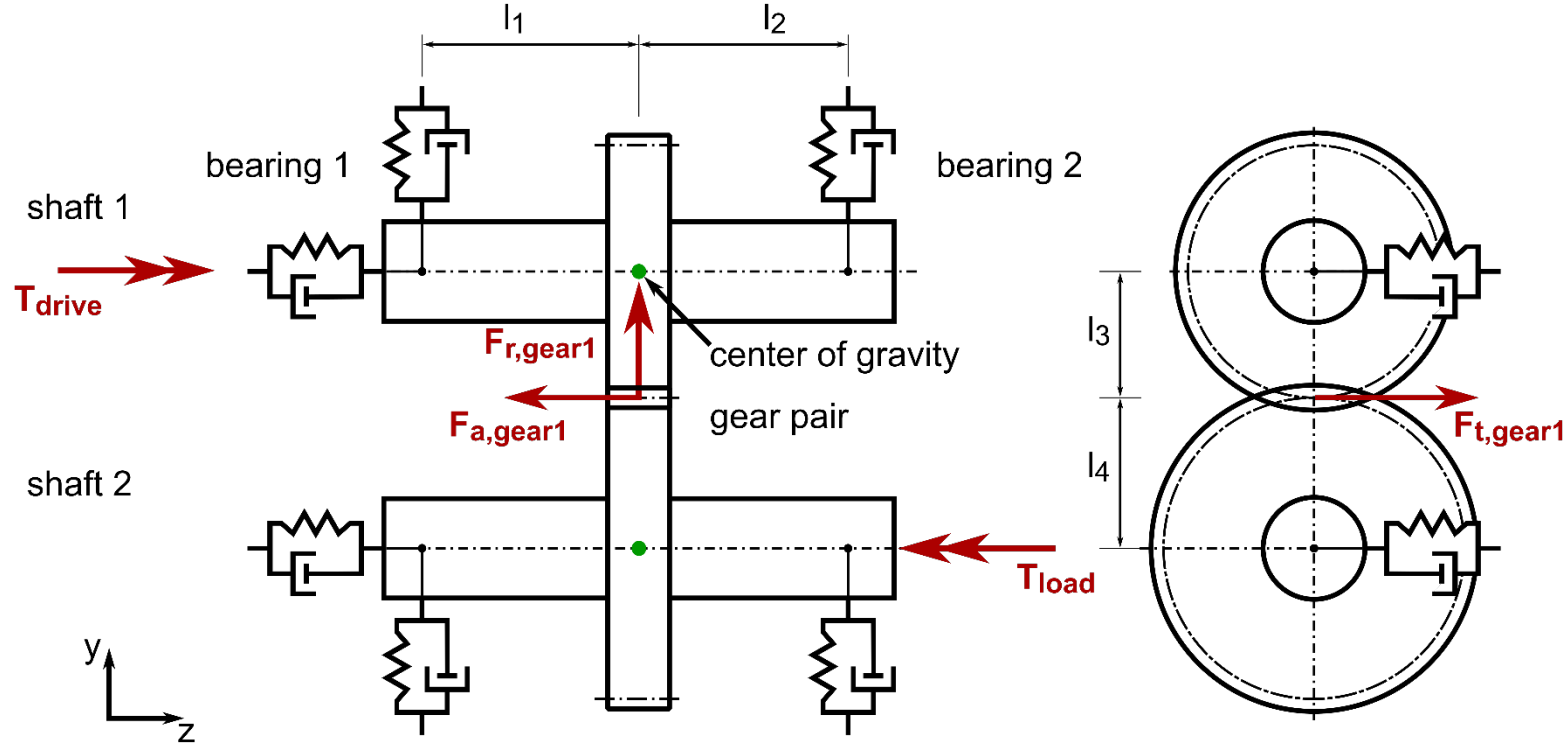


# Model Implementation

1D Tooth Mesh Simulation

# 1D Tooth Mesh Simulation

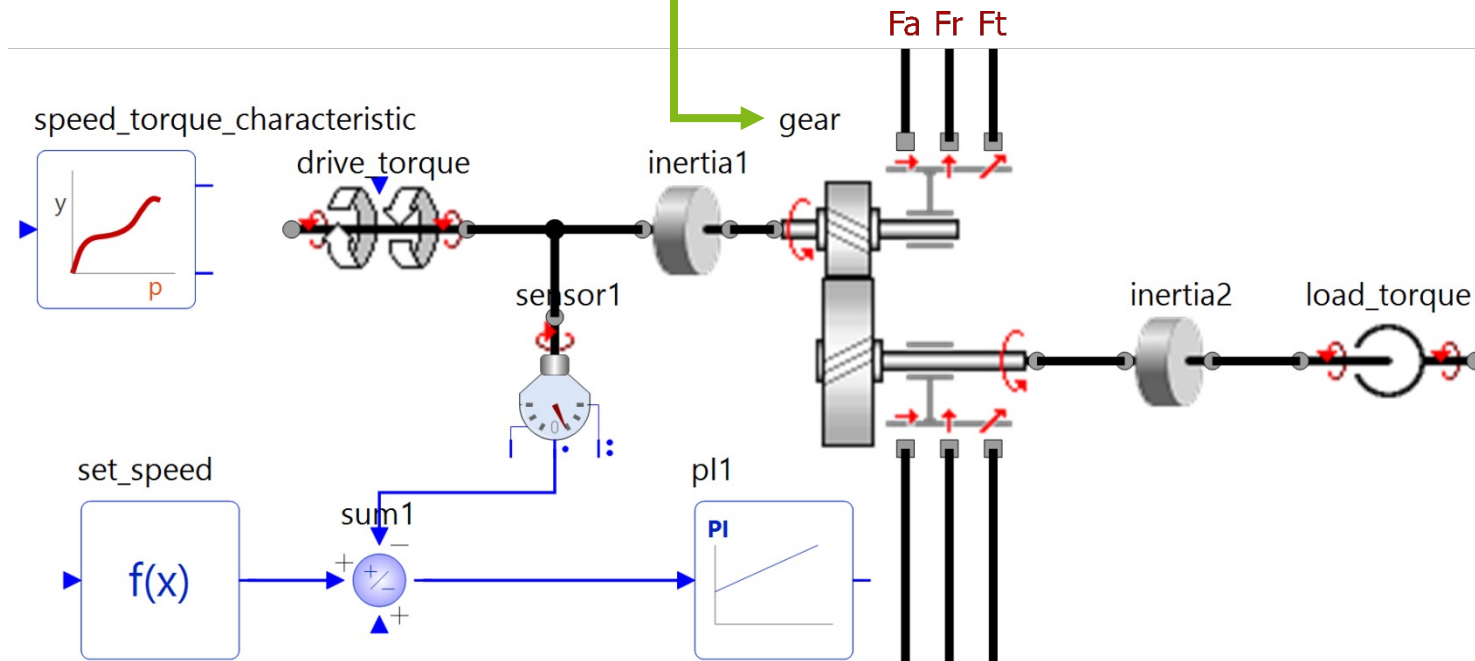
## ■ System overview



# 1D Tooth Mesh Simulation

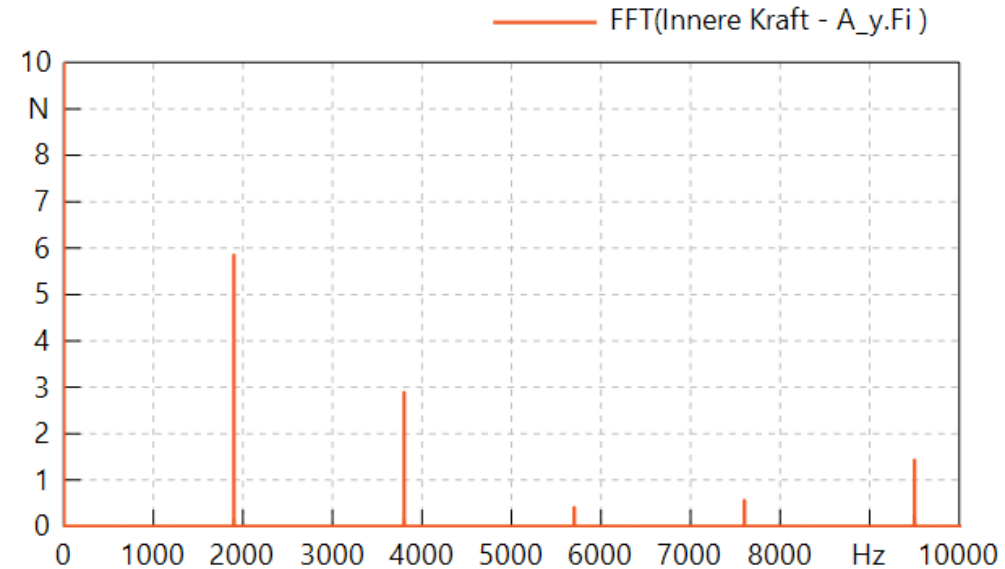
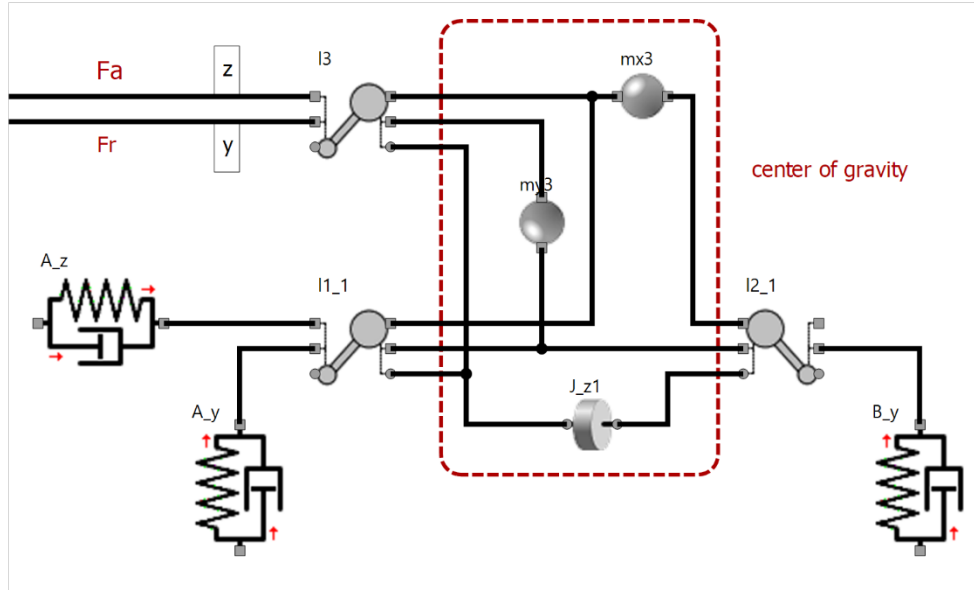
## ■ Implementation – rotational system

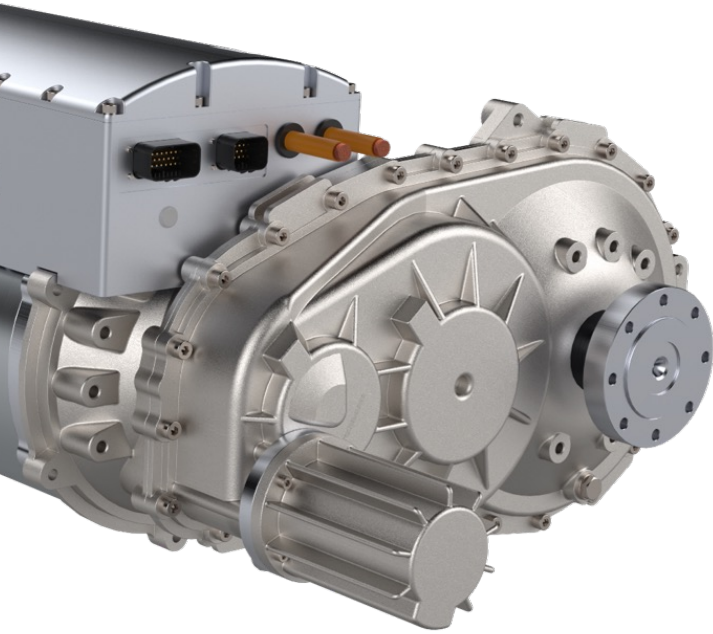
interface to the gear calculation



# 1D Tooth Mesh Simulation

- Implementation - translational system



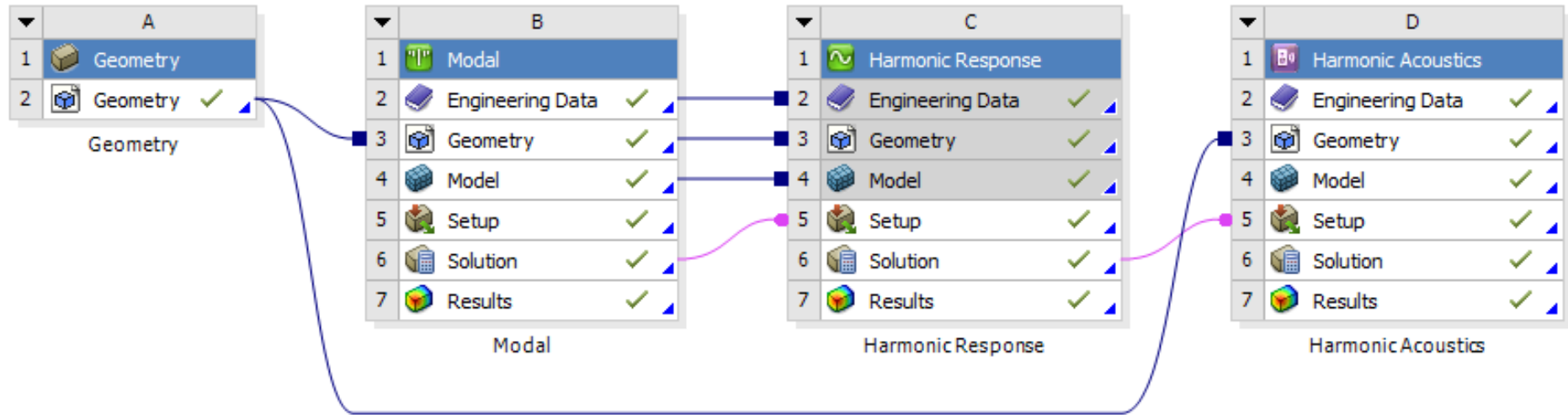


# Model Implementation

3D FEA Acoustic Simulation

# 3D FEA Acoustic Simulation

## ■ Model Implementation - Overview



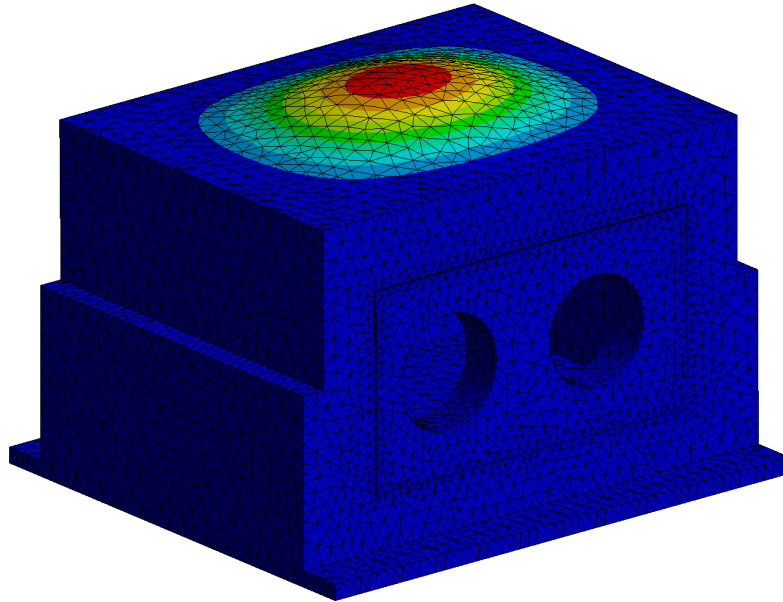
- gearbox housing
- fluid domain

- eigenfrequencies  
and their shapes

- loads from 1D Simulation
- frequency response
- structure-borne sound

- acoustic parameter
- air-borne sound

- **Modal Analysis** to determine the eigenfrequencies as well as their shapes of the gearbox housing (independent from load)



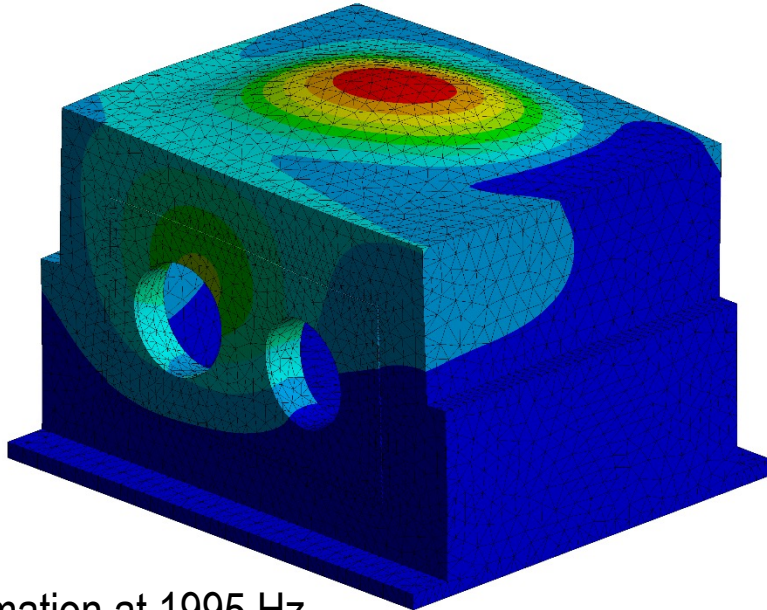
Eigenfrequency at 1995 Hz

	Auswahlmodus	<input checked="" type="checkbox"/> Frequenz [Hz]
1	1.	1995,3
2	2.	2270,2
3	3.	2438,7
4	4.	3391,
5	5.	3544,8
6	6.	3665,

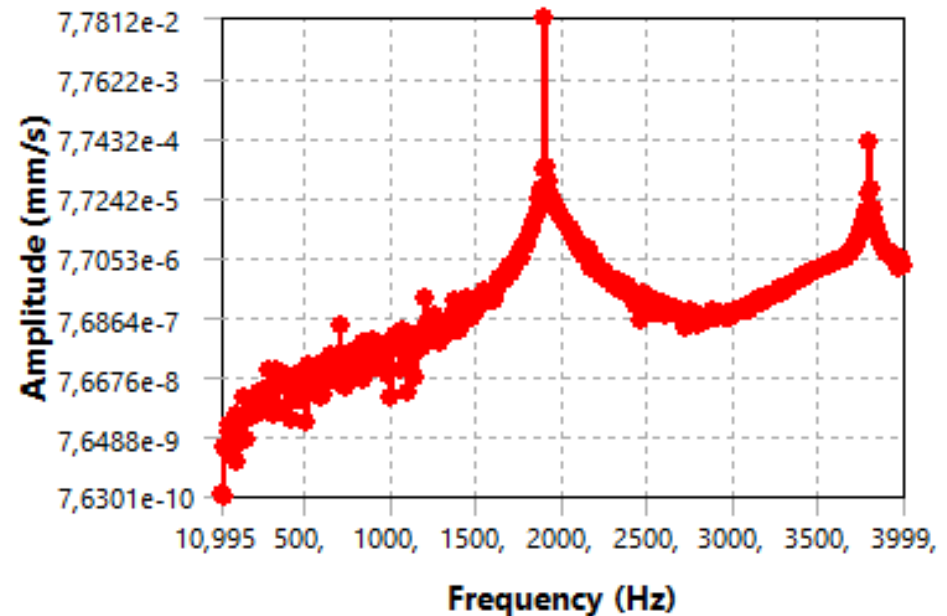


## ■ Frequency Response Analysis

- Considering the bearing loads from 1D Simulation
- Shows the frequency response of the structure

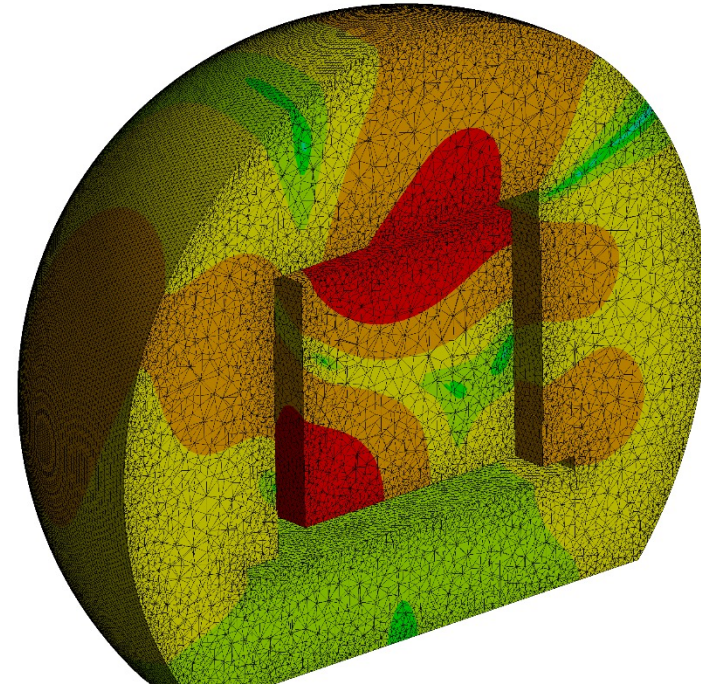
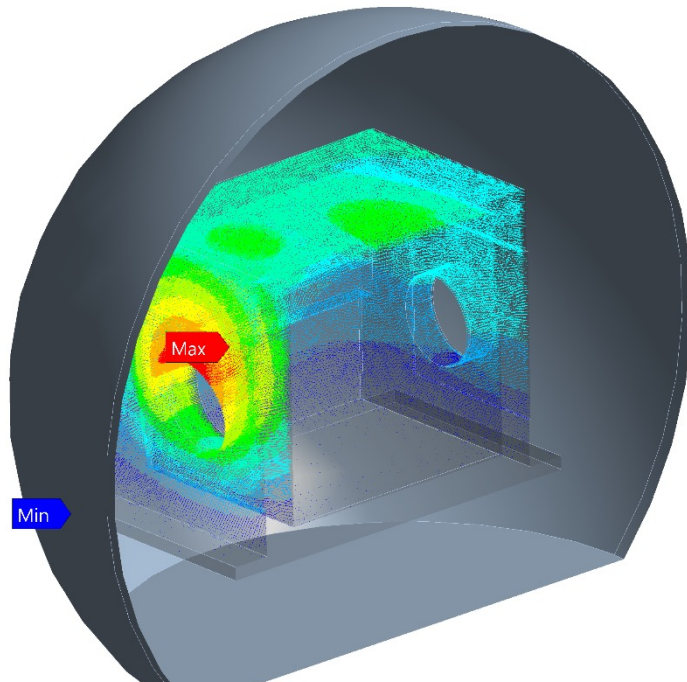


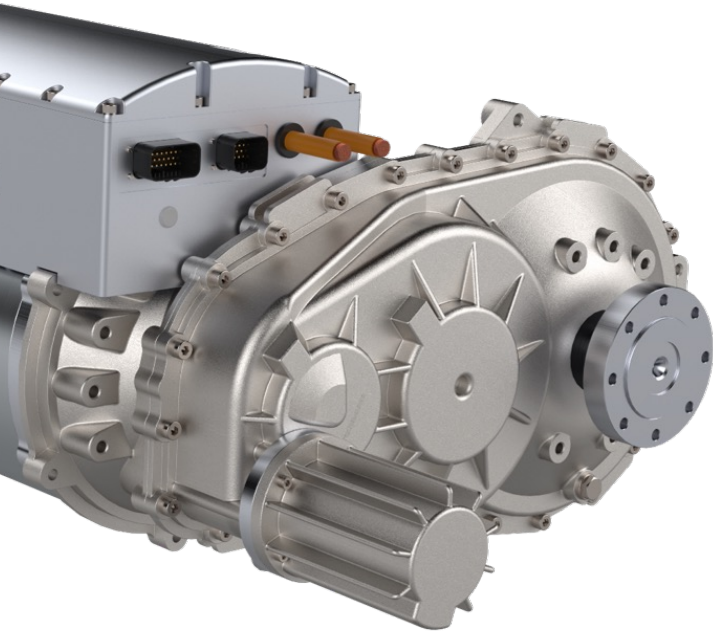
Deformation at 1995 Hz



## ■ Acoustic Simulation

- Based on the frequency response results
- Gives information about the air-borne sound





# Physical Validation Environment

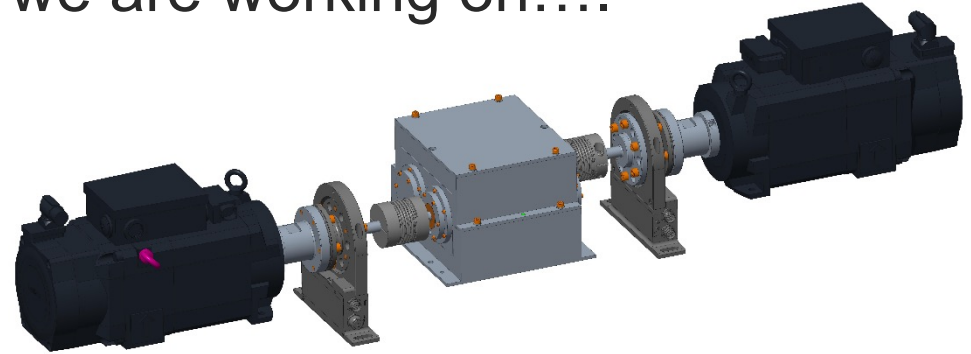
## Component and Assembly Tests

- Modal Analysis
  - For the validation of the modal analysis simulation
  - Using impulse hammer and acceleration sensors
- Operating Deflection Shape Analysis (ODS)
  - To validate the frequency response simulation
  - Gear pair test rig in operation mode
- Acoustic Analysis
  - For the validation of the acoustic simulation
  - Using structure-borne sound sensors and microphones

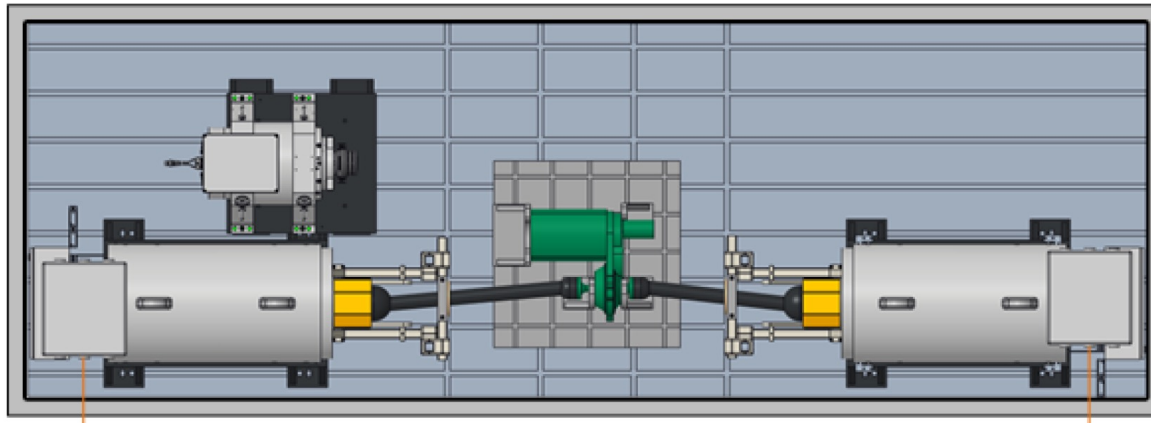


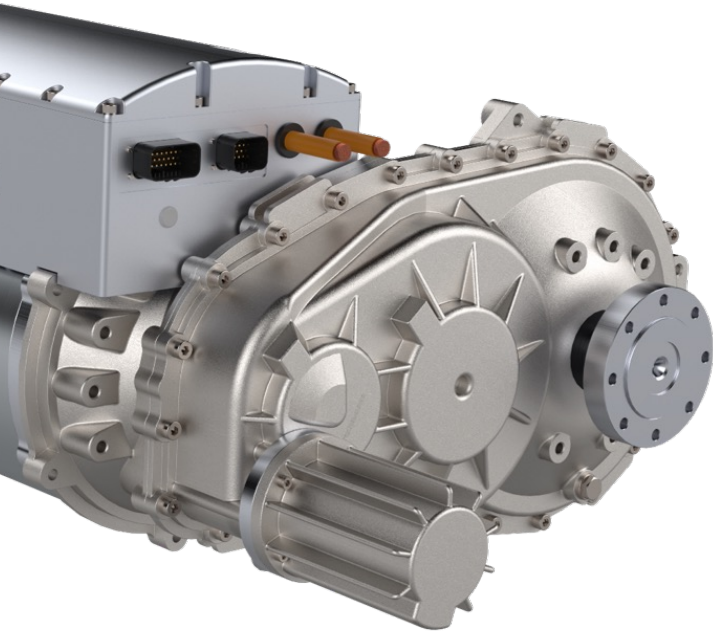


- According to the **XiL framework** we are working on....
  - ... a two motor **gear pair test rig**...



- ... and an **electric powertrain system test rig** (for LCV performance levels)





# Conclusion and Outlook

# Conclusion and Outlook

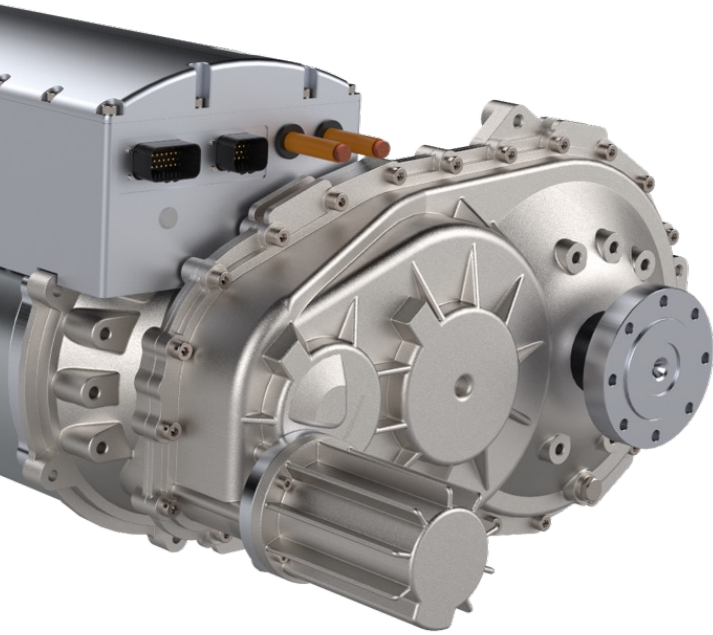
- Based on the XiL framework a **physical-virtual coupled validation environment** for noise and efficiency studies is set
- On the tooth mesh validation layer **advanced simulation model** implementations are available
- The **validation** of the tooth mesh models and the acoustic simulation as well as the realization of the test rigs are ongoing processes

- The authors are very grateful for the financial support from the Federal Ministry of Education and Research of Germany (Grant No.13FH527KA9).

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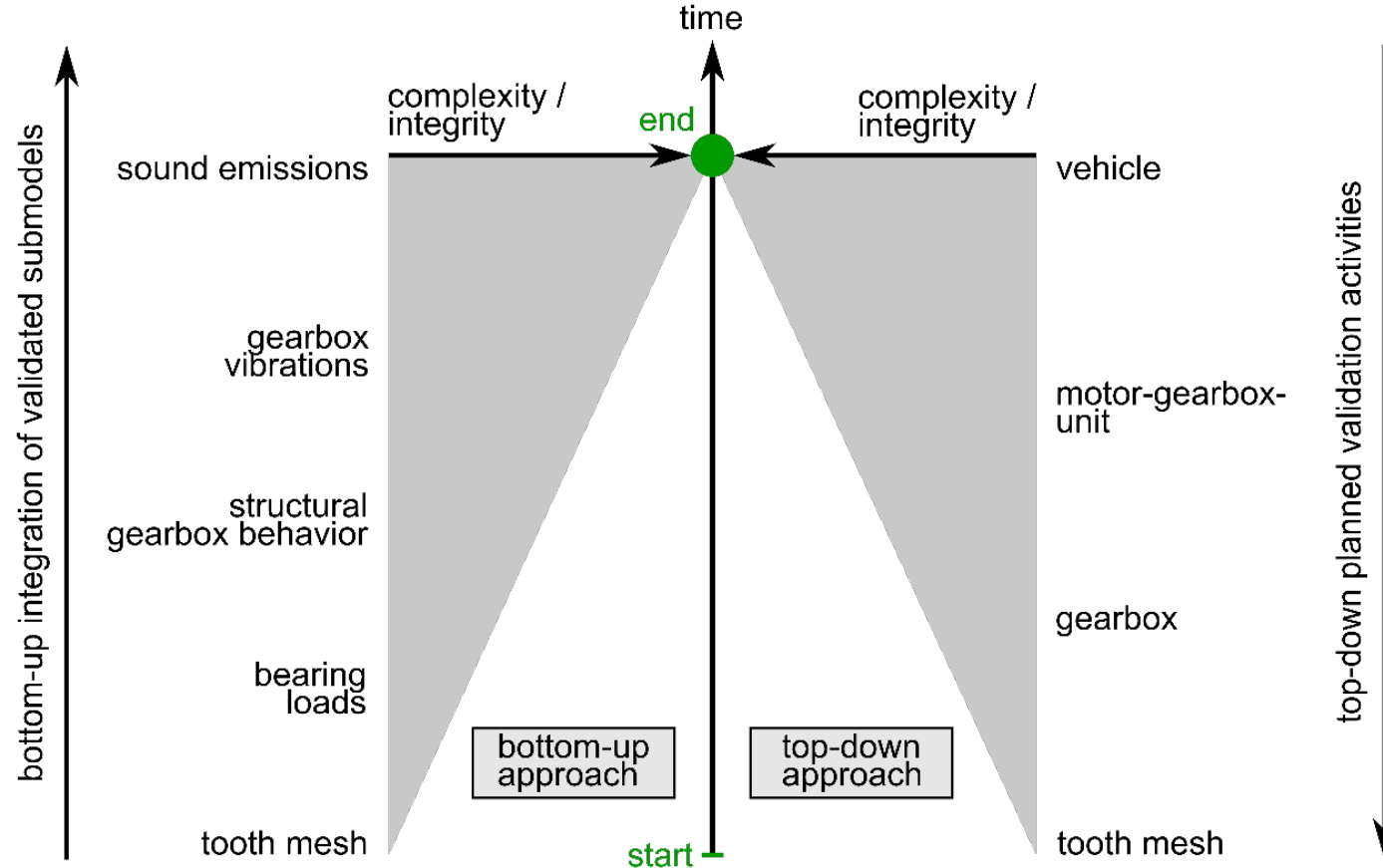
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# Extended Validation Approach



# 1D Tooth Mesh Simulation

