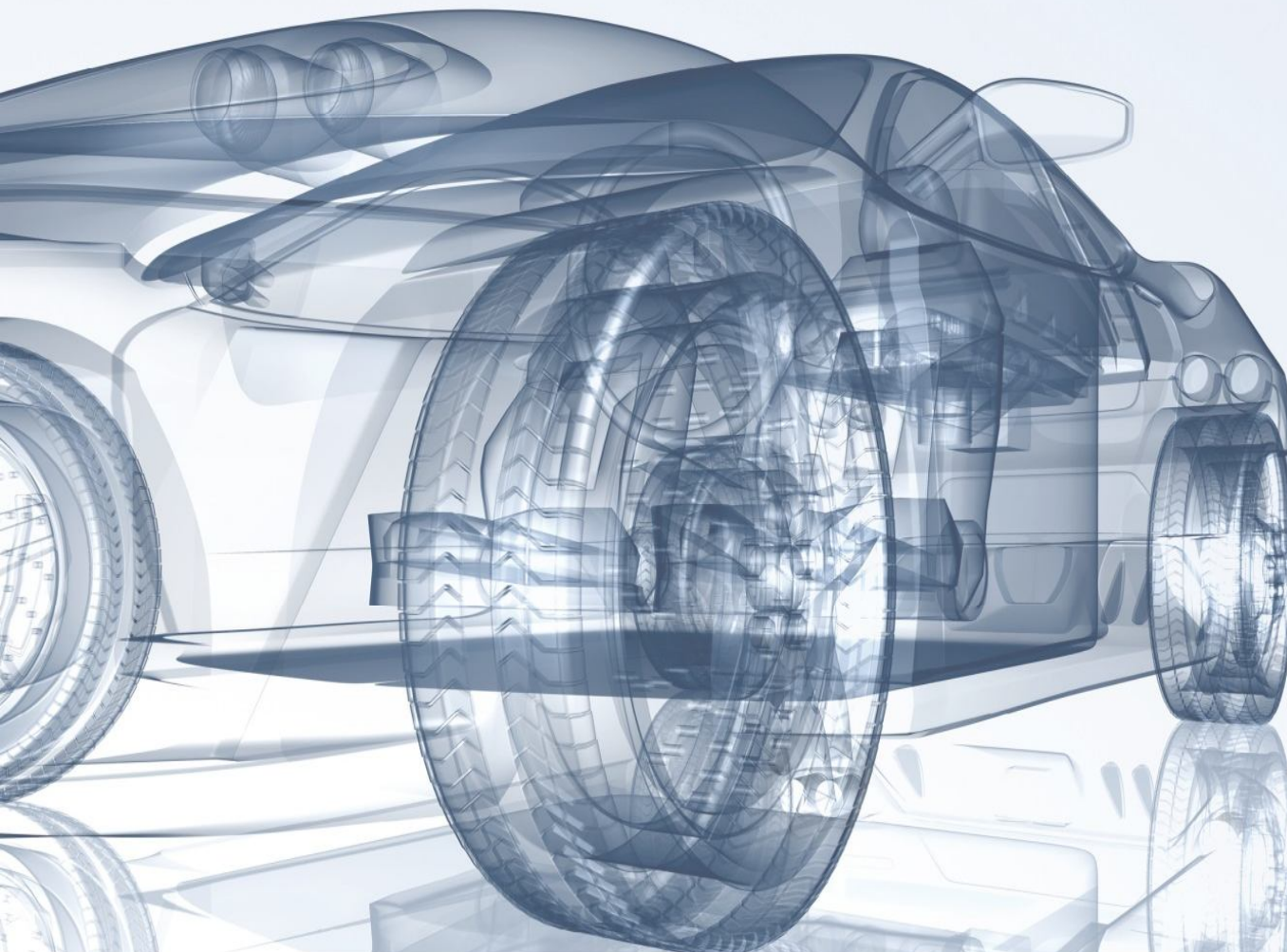


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A Study of Electric Vehicle Wireless Charging System Integration and Vehicle Alignment Optimization

2017. 10. 10

Hyundai Motor Company
Research & Development Division
Jaeyong Seong, Senior Research Engineer

Agenda

I. Introduction

II. Integration

III. Results

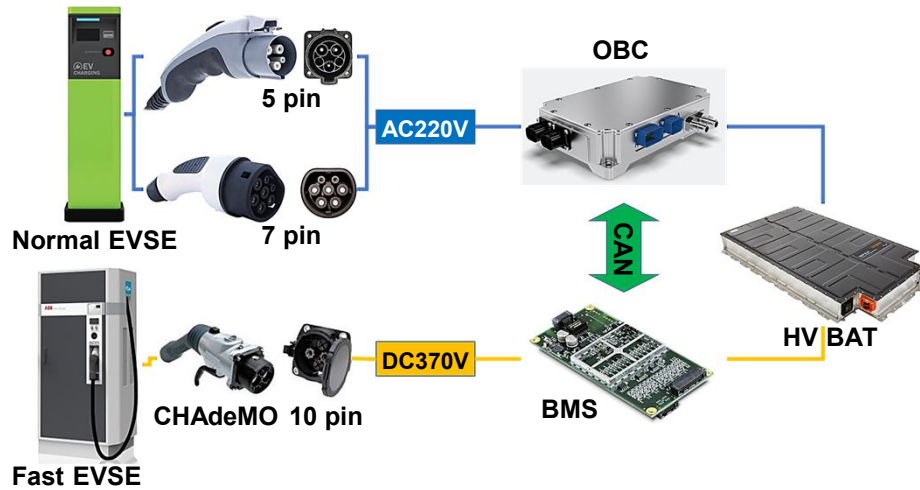
IV. Conclusion

I. Introduction

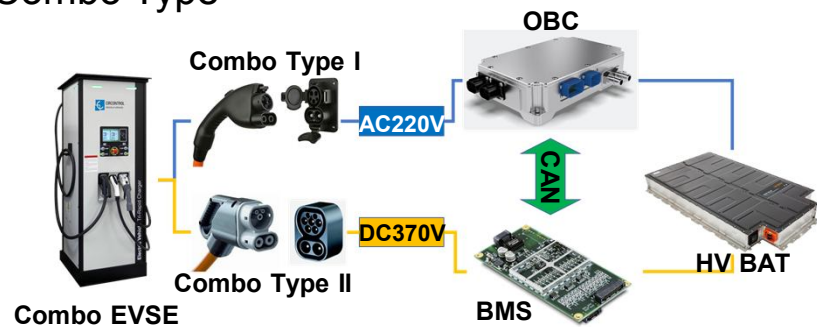
1. Electric Vehicle Charging System

Conductive Charging

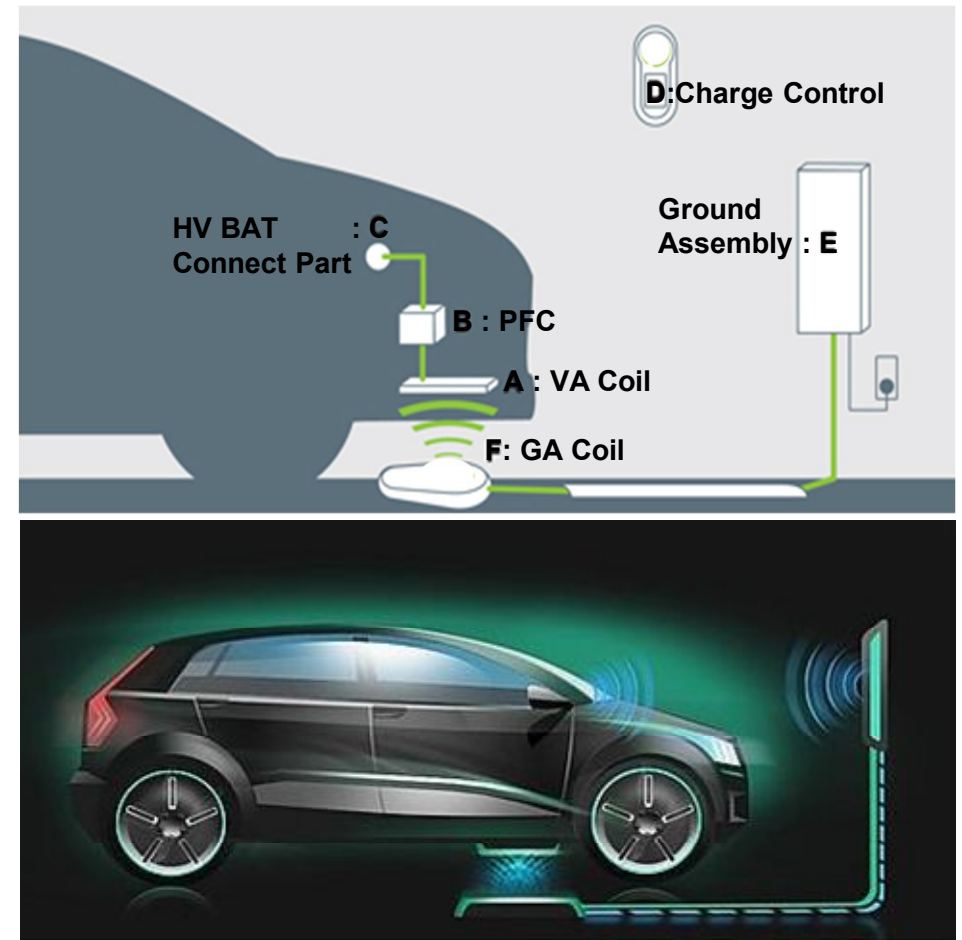
1) Normal / Fast separable Type



2) Combo Type

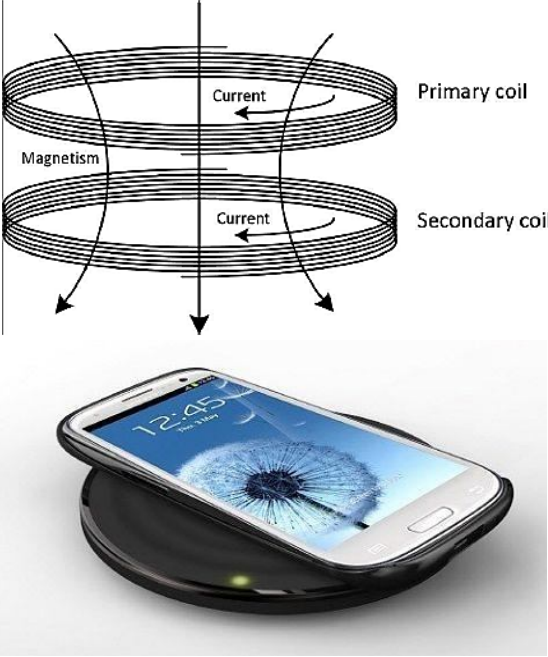
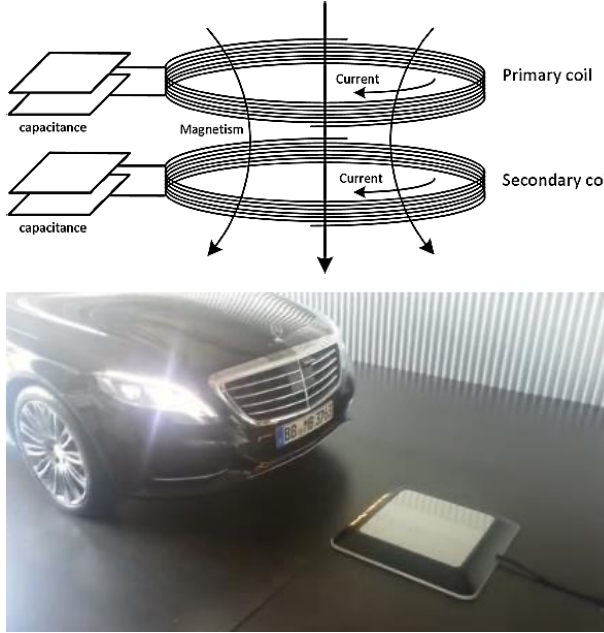
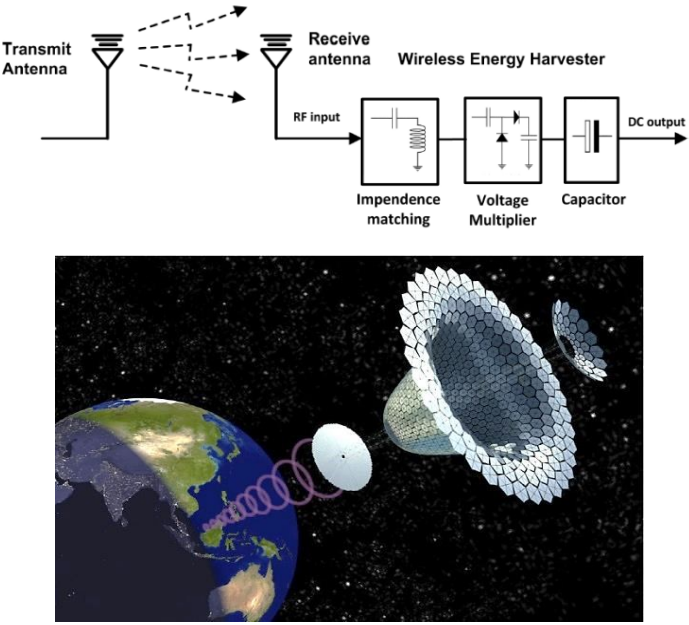


Wireless Charging



I. Introduction






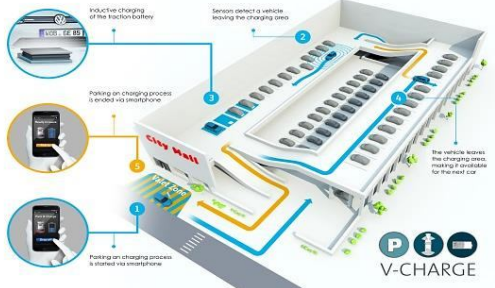
2. Wireless Charging Technologies

Inductive	Magnetic Resonance	Microwave
<ul style="list-style-type: none"> • Magnetic field induction • Charging distance : mm ~ cm • Ease of implementation • Applicable(ex. mobile devices) 	<ul style="list-style-type: none"> • Two resonant coil oscillating magnetic field • Charging distance : cm ~ m • Loose alignment 1st & 2nd coils • High energy transfer(ex. EV) 	<ul style="list-style-type: none"> • Utilizes diffused microwave as a medium to carry radiant energy • Charging distance : several tens of m • Powercaster or powerharvester • Due to the safety issue 

I. Introduction

3. EV WPT Trend

➤ Cooperation development of technology between vehicle OEM and charger supplier

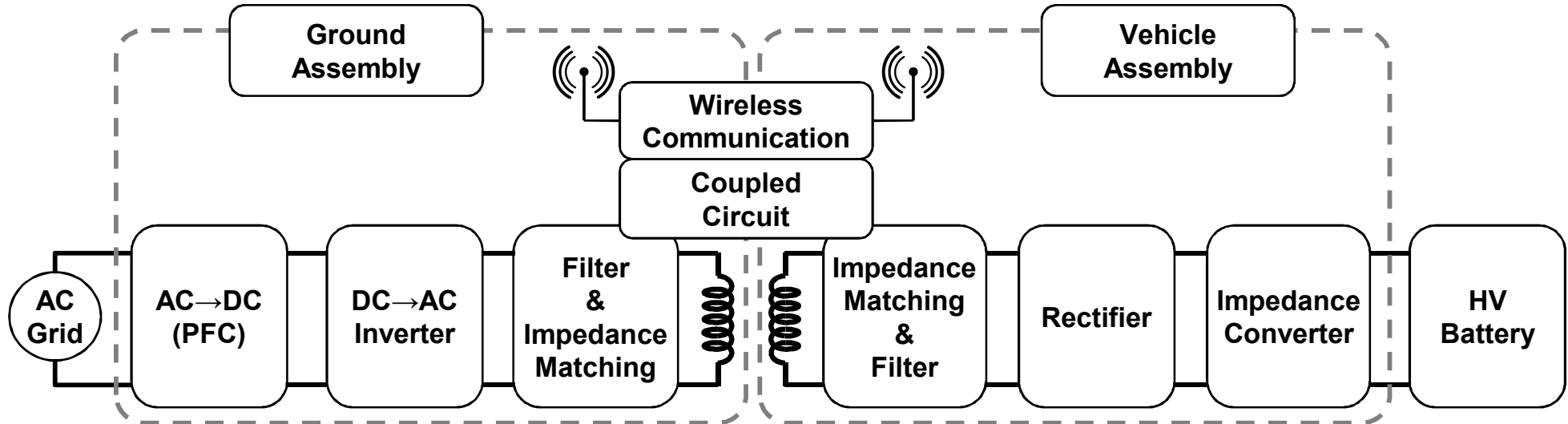
	OEM / Supplier	Supplier	Manufacture
<p>OEM & Supplier</p>	<ul style="list-style-type: none"> • Demonstrated WPT for EV ('15 CES) • Contributions to ISO/IEC Standards. (ISO 19363 / IEC 61980) 	<ul style="list-style-type: none"> • Aftermarket products - Nissan Leaf 12MY / 13MY - GM Volt customers ('14.6) 	<ul style="list-style-type: none"> • Daimler S550 PHEV('18) • BMW 530e PHEV('18) • Toyota Prius PHEV ('17) 
	GA / VA coils	Alignment	Smart Charging
<p>Technologies</p>	<ul style="list-style-type: none"> • High Capacity WPT Coil: 10kW↑ 	<ul style="list-style-type: none"> • Low power excitation, etc. 	<ul style="list-style-type: none"> • Optimal charging using V2G 

Presenter: Jaeyong Seong, Hyundai Motor Company

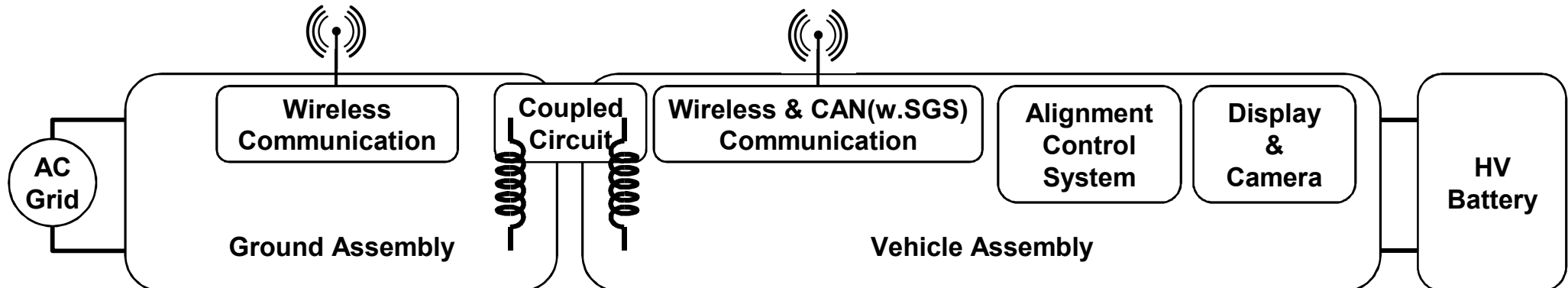
II. Integration

1. Block Diagram of WPT for xEV

➤ SAE J2954 TIR

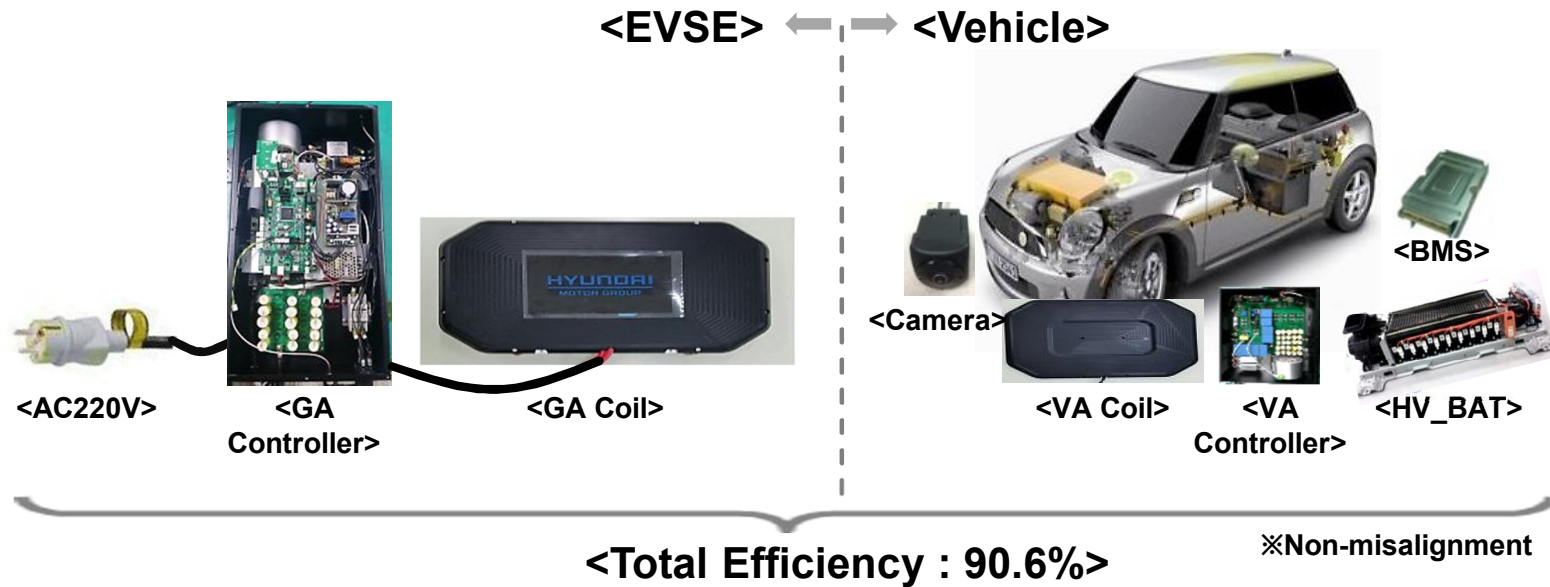


➤ Based on SOUL EV



II. Integration

2. Implementation of Proto-type WPT in SOUL EV



	GA Coil size	VA Coil size	Z Height	Topology	Operation Freq.	Max. input Power	Efficiency
Proto-type	650x470x60 mm	250x250x20 mm	165 mm	Circular	85 kHz	3.7 kW	90.6 %
ref.SAE	675x590x60 mm	355x355x20 mm	140~210 mm (Z2 Class)	Circular	81.38 ~ 90kHz	0 ~ 3.7 kW	85 %↑

II. Integration

2. Implementation of Proto-type WPT in SOUL EV

	GA Coil	VA Coil
Coil Part		
Power Part		

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II. Integration

3. GA Coil Recognition & Position Alignment

➤ Video capture & correction

Algorithm	Result	
<pre> graph TD A[Input Fr. Camera] --> C[Video Capture] B[Input CAN Interface] --> C </pre>	<p>Original image input through wide-angle camera</p>	<p>Distortion correction using lens distortion model</p>

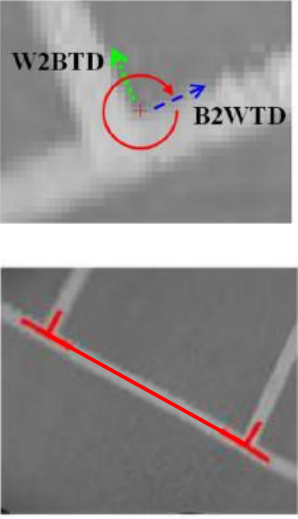

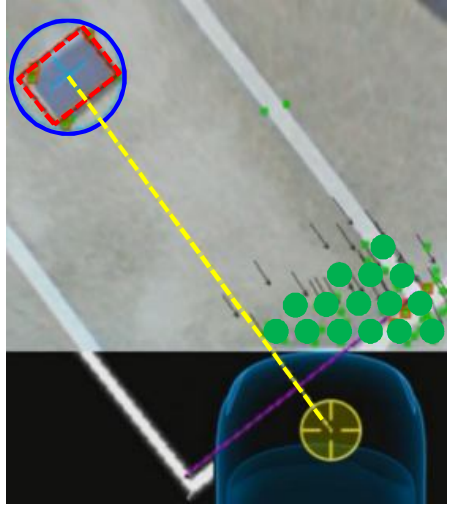
➤ Top view & recognition region

Algorithm	Result	
<pre> graph TD A[Top View Transform] --> B[Image Duplicate & Copy] </pre>	<p>Perspective transform & Top view change</p>	<p>Image Duplicate & Copy(560X500 YUV420SP)</p>

II. Integration

3. GA Coil Recognition & Position Alignment

➤ Detection of parking space & GA coil

Algorithm	Result		
<pre> graph TD A[Image Pre-processing] --> B[Recognition Parking Line] A --> C[Recognition GA Coil] A --> D[Position Tracking] B --> E[Image Merge & Sync.] C --> E D --> E E --> F[Final Image] F --> G[Output LCD] </pre>	 <ul style="list-style-type: none"> •Parking space detection •Corner detection •Check the corner type 	 <ul style="list-style-type: none"> •Setting of GA coil recognition area •Corner detection of GA coil •Check the corner type of GA Coil •Shape detection of GA coil package 	 <ul style="list-style-type: none"> •Calculation of feature point change between video frames •Calculating the rotation center and rotation angle of a vehicle •Position calculation using rotation center and rotation angle

III. Results

1. Test Result of Efficiency and Positioning Tolerance

	Coordinate System	Spec.	Result
X axis Y axis		$\Delta X : \pm 75\text{mm}$ $\Delta Y : \pm 100\text{mm}$ Effi. : 85%↑	
Z axis		$Z1 : 100\sim 150\text{mm}$ $Z2 : 140\sim 210\text{mm}$ $Z3 : 170\sim 250\text{mm}$ Effi. : 85%↑	

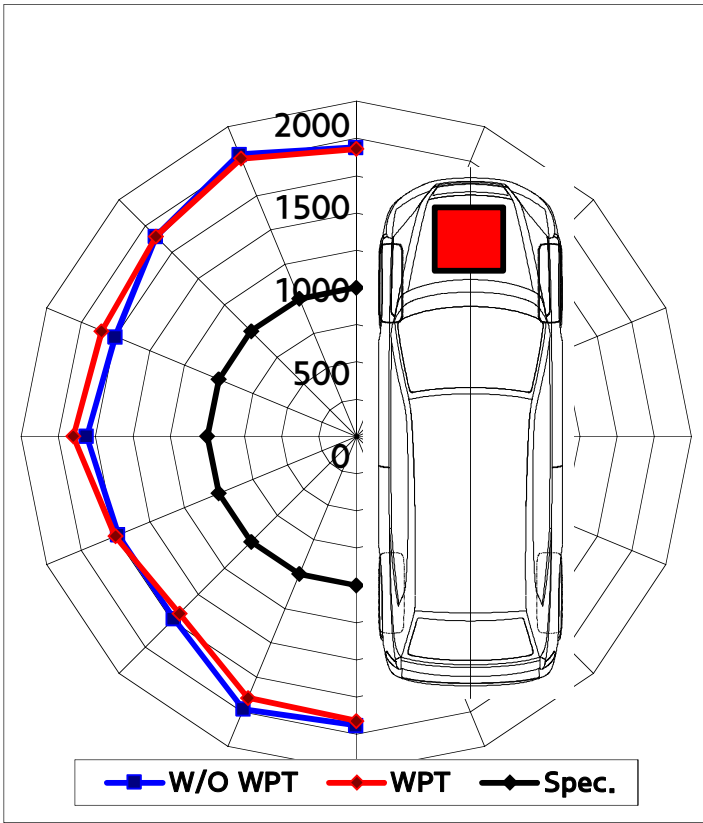
III. Results

2. Test Result of EMF

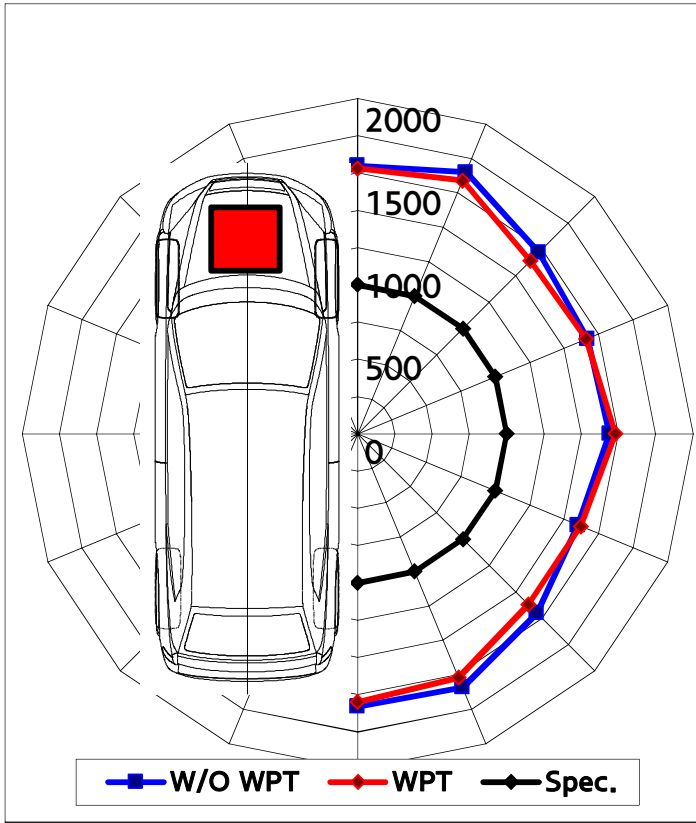
	Measure Point	EMF Result
Vehicle Outside	<p>Measure Height 50 / 300 / 600 / 900 / 1200mm</p>	<p>EMF [μT]</p> <p>Measure Height</p> <p>50mm 300mm 600mm 900mm 1200mm</p> <p>1. Front 2. Side Rear Right 3. Side Rear Left 4. Rear</p>
Vehicle Inside		<p>EMF [μT]</p> <p>Seat position</p> <p>Driver Passenger Rear Left Rear Right</p> <p>A. Head B. Chest</p>

III. Results

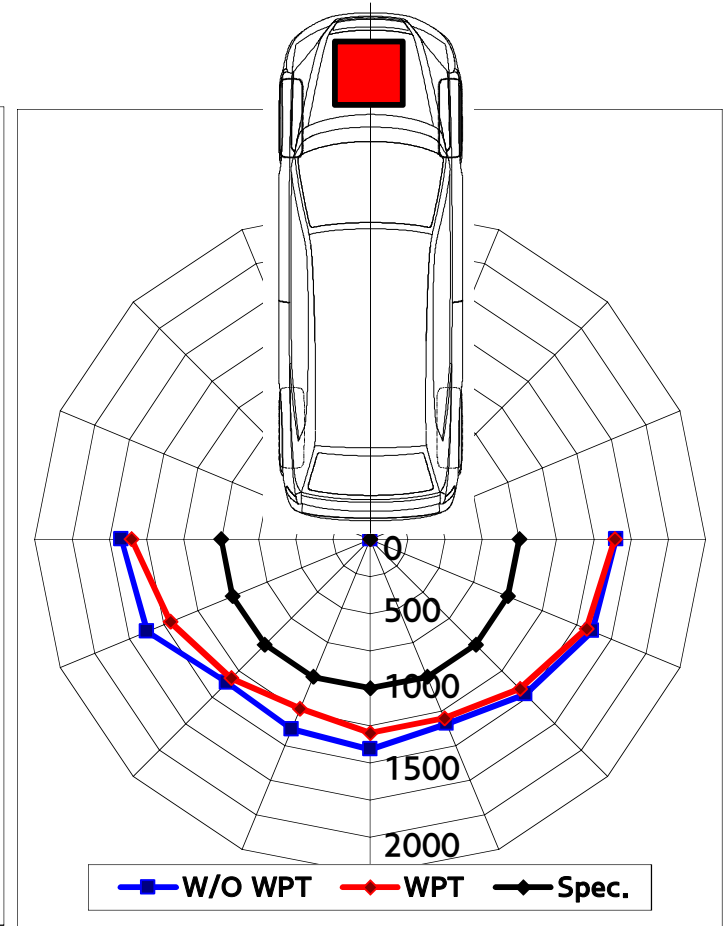
3. Test Result of Interference



<Driver Door>



<Passenger Door>



<Tail Gate>

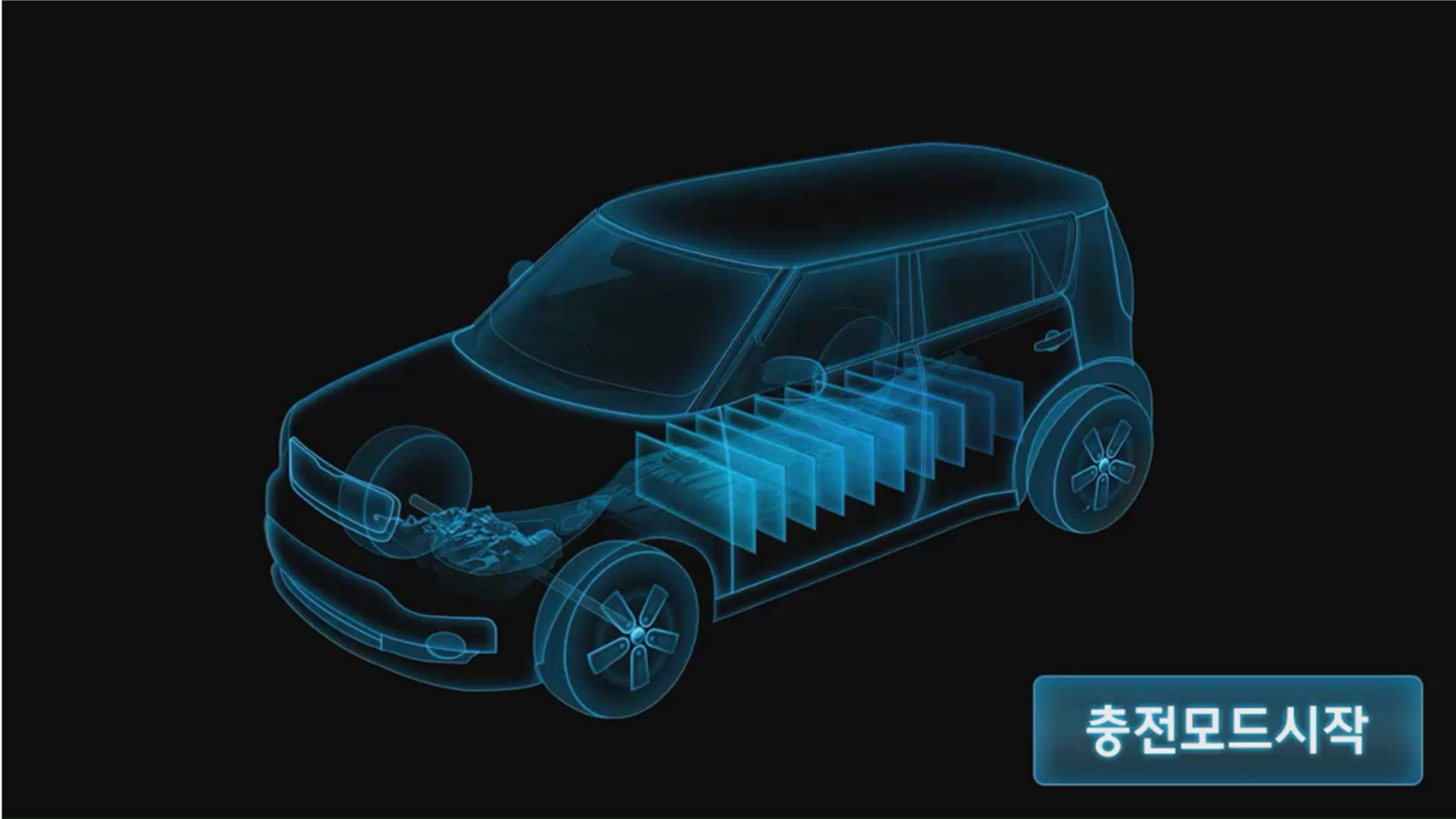
III. Results

3. Test Result of Primary Coil Recognition and Alignment

Experiment	Result																																																													
<p>1st stage recognition of GA coil</p>	<p>Avr. recognition 94%</p> <table border="1"> <caption>Data for 1st Stage Recognition (Algorithm vs Measurement)</caption> <thead> <tr> <th>Distance X axis</th> <th>Distance Y axis (Algorithm)</th> <th>Distance Y axis (Measurement)</th> </tr> </thead> <tbody> <tr><td>-1200</td><td>3730</td><td>4000</td></tr> <tr><td>-1000</td><td>3740</td><td>4000</td></tr> <tr><td>-500</td><td>3810</td><td>4000</td></tr> <tr><td>-200</td><td>3800</td><td>4000</td></tr> <tr><td>0</td><td>3790</td><td>4000</td></tr> <tr><td>100</td><td>3720</td><td>4000</td></tr> <tr><td>500</td><td>3810</td><td>4000</td></tr> <tr><td>1000</td><td>3740</td><td>4000</td></tr> <tr><td>1200</td><td>3680</td><td>4000</td></tr> </tbody> </table>	Distance X axis	Distance Y axis (Algorithm)	Distance Y axis (Measurement)	-1200	3730	4000	-1000	3740	4000	-500	3810	4000	-200	3800	4000	0	3790	4000	100	3720	4000	500	3810	4000	1000	3740	4000	1200	3680	4000	<p>Avr. recognition 92%</p> <table border="1"> <caption>Data for 1st Stage Recognition (Algorithm vs Measurement)</caption> <thead> <tr> <th>Distance X axis</th> <th>Distance Y axis (Algorithm)</th> <th>Distance Y axis (Measurement)</th> </tr> </thead> <tbody> <tr><td>-1200</td><td>530</td><td>600</td></tr> <tr><td>-1000</td><td>550</td><td>600</td></tr> <tr><td>-500</td><td>560</td><td>600</td></tr> <tr><td>-200</td><td>560</td><td>600</td></tr> <tr><td>0</td><td>550</td><td>600</td></tr> <tr><td>100</td><td>550</td><td>600</td></tr> <tr><td>500</td><td>560</td><td>600</td></tr> <tr><td>1000</td><td>560</td><td>600</td></tr> <tr><td>1200</td><td>540</td><td>600</td></tr> </tbody> </table>	Distance X axis	Distance Y axis (Algorithm)	Distance Y axis (Measurement)	-1200	530	600	-1000	550	600	-500	560	600	-200	560	600	0	550	600	100	550	600	500	560	600	1000	560	600	1200	540	600
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III. Results

4. Alignment Video



Presenter: Jaeyong Seong, Hyundai Motor Company

IV. Conclusion

➤ Integration 3.3kW wireless charging prototype in a Soul EV

: Input Source AC 220V, Charging Capacity 3.3kW, Charging Efficiency 90.6%

➤ Implementation of GA Coil Recognition & Position Alignment System

: Perspective & Top view transformation model

Parking space recognition & position tracking

➤ Ground Assembly Coil Detection

: The recognition rate of the actual vehicle evaluation result is more than 90%.

➤ Future Plan

: Development of wireless charging position alignment method using LF antenna

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