

Holistic Methodology for Generating Customer-Related Testing Profiles for Electrified Powertrains

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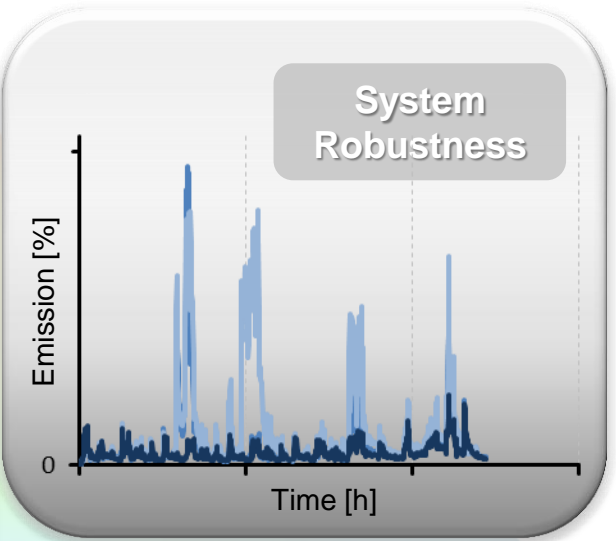
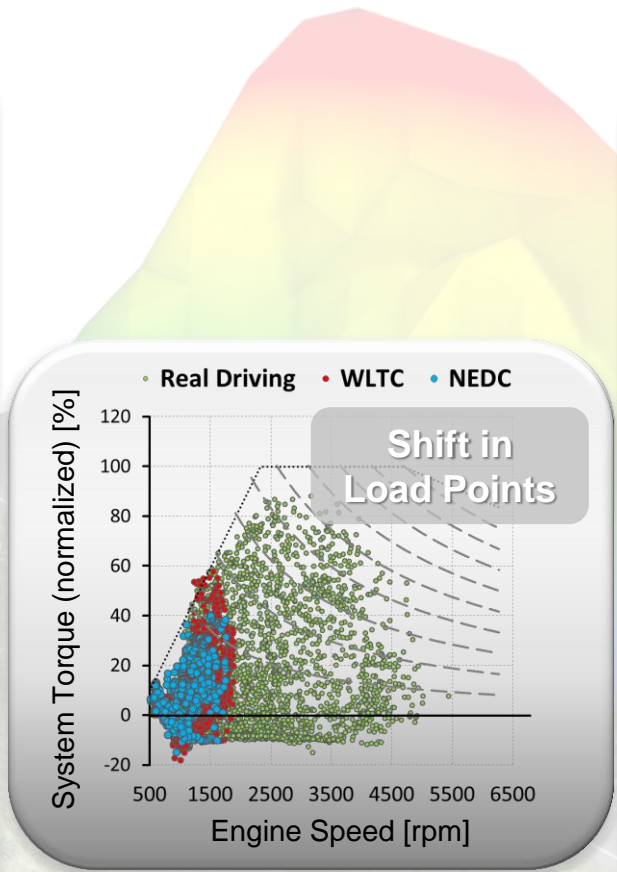
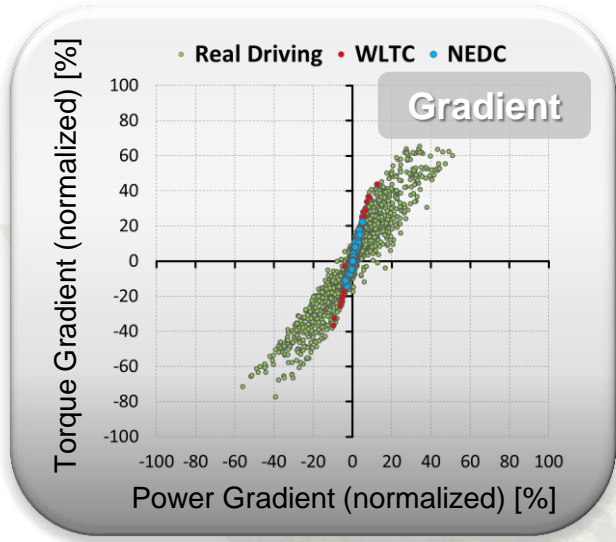
EVS30 - Electric Vehicle Symposium 2017
Stuttgart, October 9th - 11th, 2017

- Motivation
- Transfer of the „Road2Dyno“-Method to Electrified Powertrains
- Summary

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APL Group - Motivation

New Requirements due to RDE Legislation

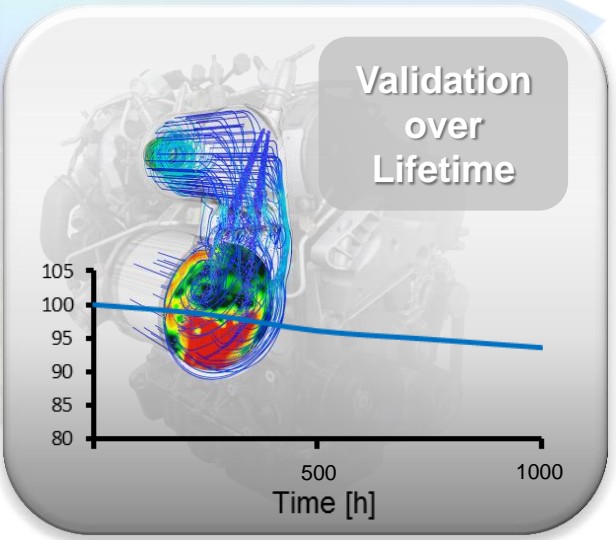


Topography

Environment Boundary Conditions

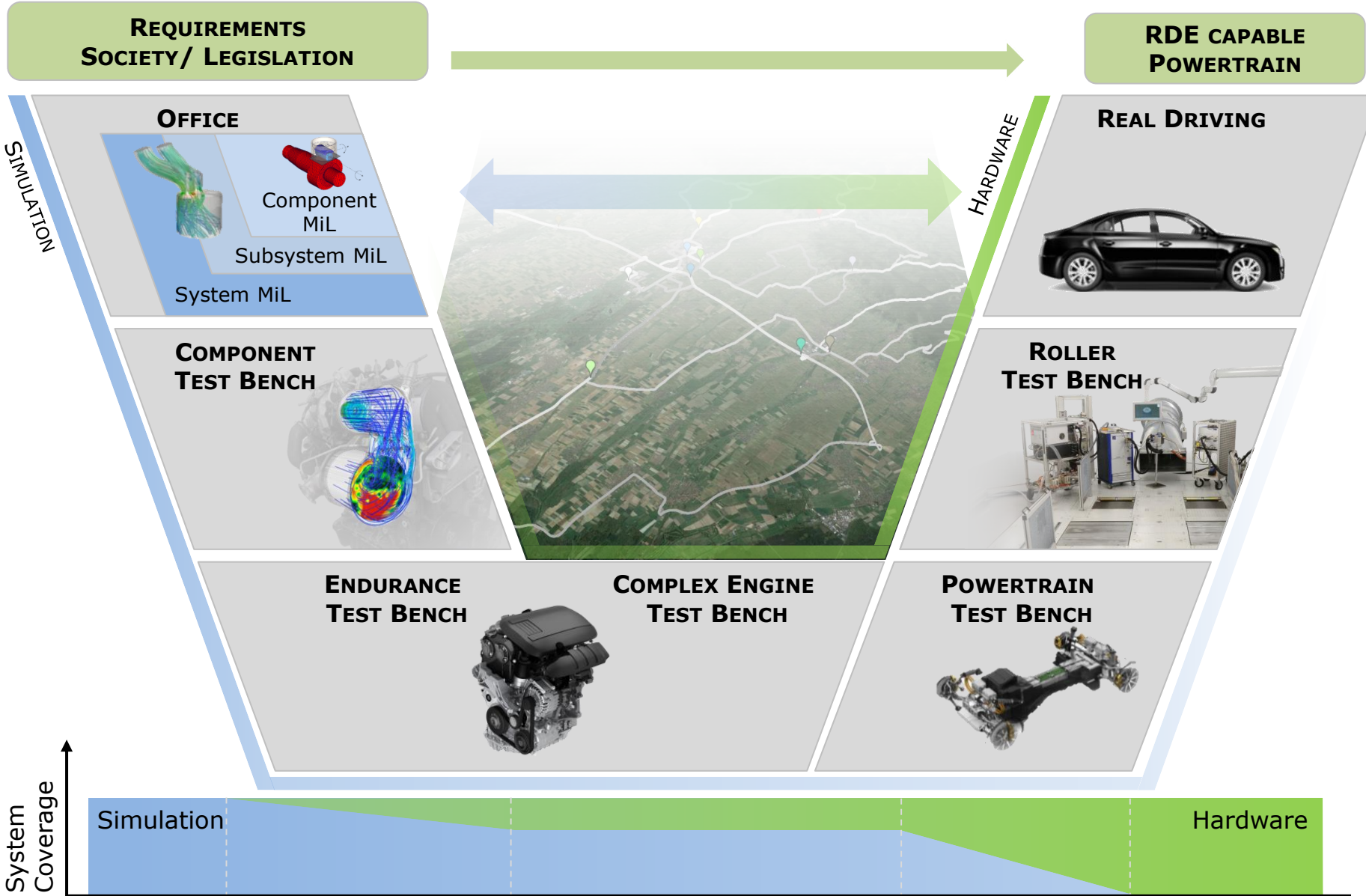
Traffic

Climate



APL Group - Motivation

RDE and the Impact on the Development Process





DEGREE OF ELECTRIFICATION

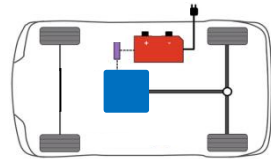
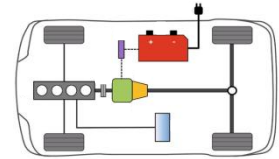
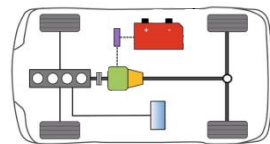
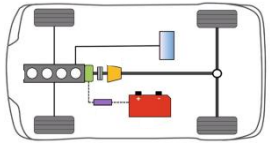
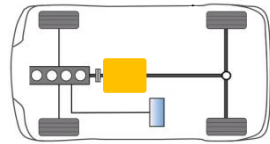
ICE

MILD-HYBRID

FULL-HYBRID

PLUGIN-HYBRID

BEV



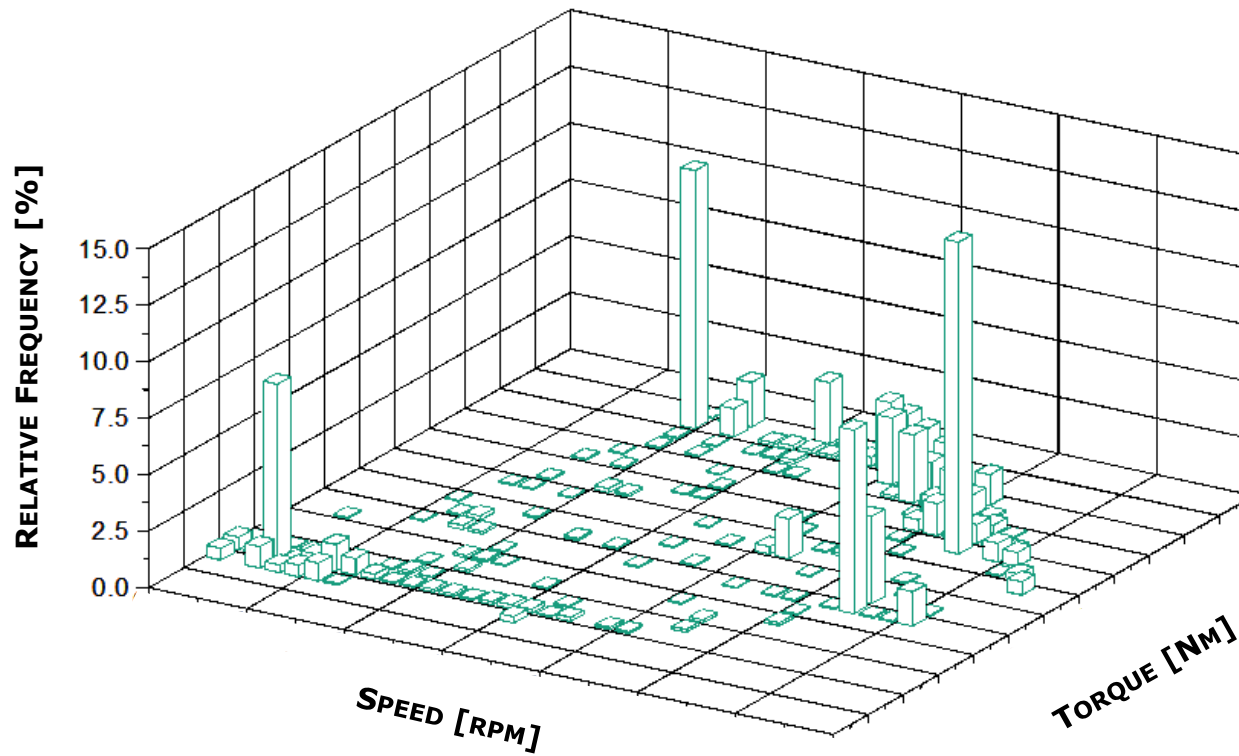
**NEW REQUIREMENTS IN REGARD TO MECHANICAL COMPONENTS:
 SHIFTING LOAD SPECTRA AS RESULT OF USAGE MARKET, ENVIRONMENTAL CONDITIONS &
 DRIVING STYLE**



VOLTAGE **12 V** **48 V** **200 V** **400 V** **800 V**

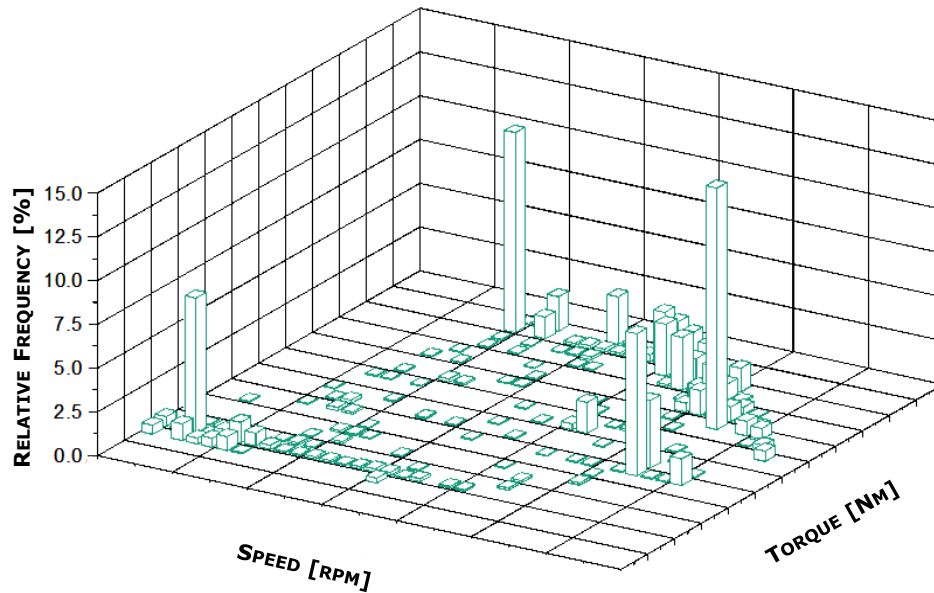


ELECTRIC COMPONENTS **BATTERY CAPACITY, POWER ELECTRONICS, ...**



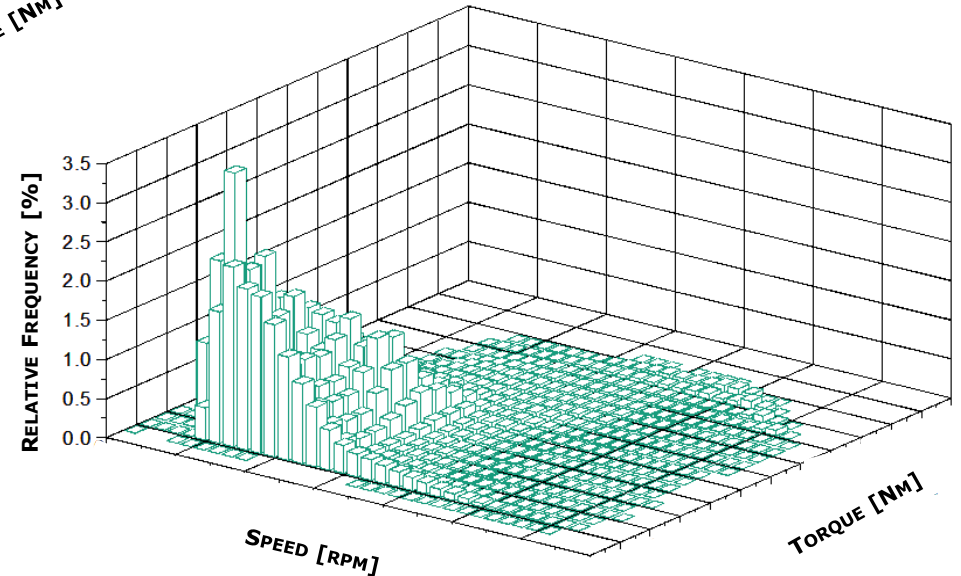
- Driver's Profile?
- Correct Testing?
- Time and Cost Savings in Testing?

Test Bench vs. Vehicle



Endurance Test on Engine Test Bench

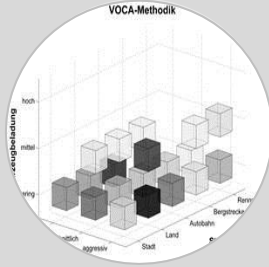
Load Spectra Real Driving



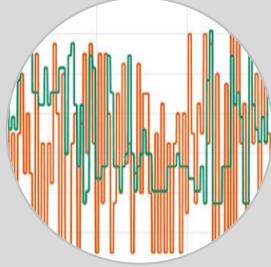
- Motivation
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Enquiry of
Real Driving Data



Determination of
representative
Load Spectra
by VOCA



Derivation of
Testing Profiles
with SDC-Tool



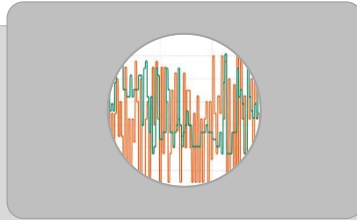
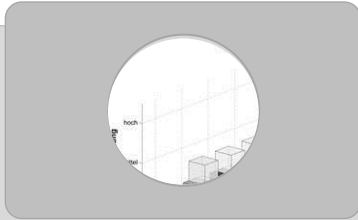
Integration of
Acceleration Factors
with GenETeC



Database
Management

Method „Road2Dyno“

Step 1 - Enquiry of Real Driving Data



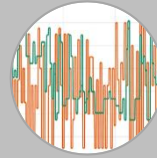
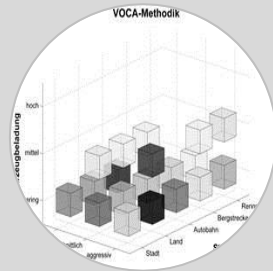
Enquiry of Real Driving Data:

Usage of a CAN-Datalogger:

- Access to Vehicle-CANBus
- Datatransmission via UMTS
- Automated Data Validation & Analysis

Signal	Frequency (Hz)
Engine Speed (ICE)	2
Engine Torque (ICE)	2
Engine Speed (E-Motor)	2
Engine Torque (E-Motor)	2
State of Charge (SOC)	2
Vehicle Speed	2
Accelerator Pedal Position	2
Gear	2
Steering Angle	2
GPS Altitude	2
Longitudinal Acceleration	10
Lateral Acceleration	10





Determination of representative Load Spectra with VOCA – Vehicle Operating Condition´s Analysis:

Definition of Customer Usage Condition:

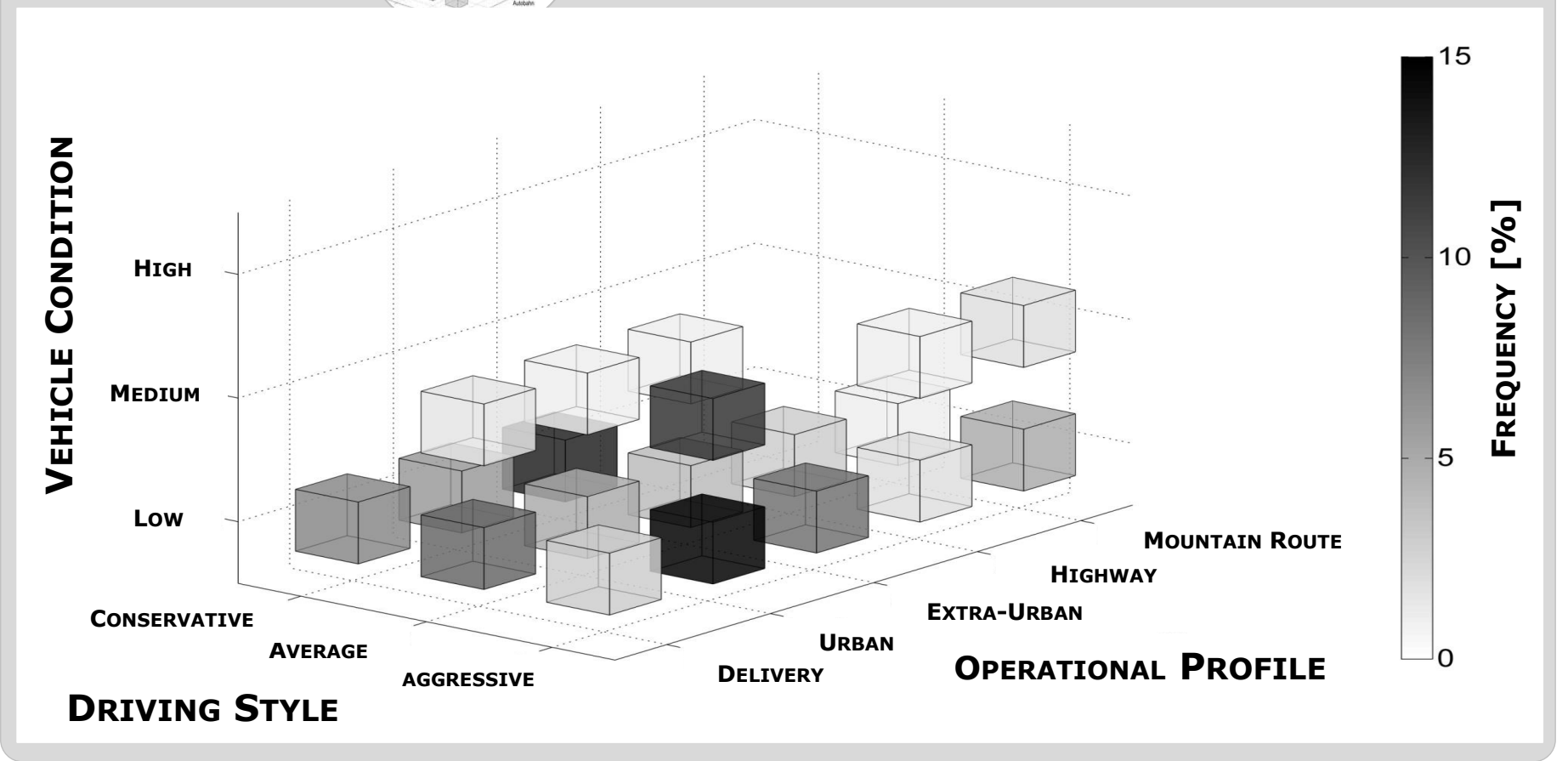
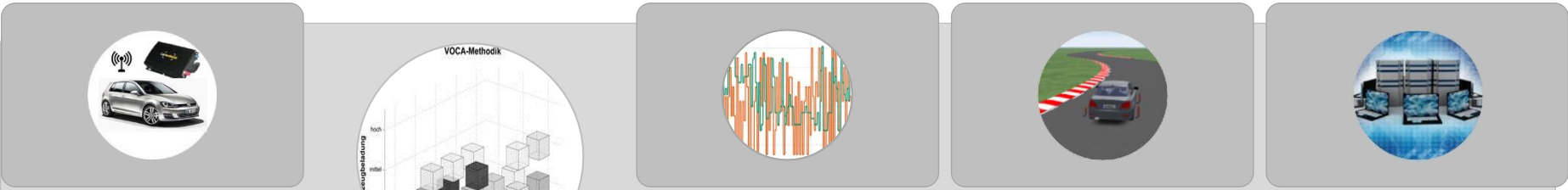
- Virtual Space which contains all statistically relevant Types of Customers
- Based on 3F-Parameterraum (TU Braunschweig)

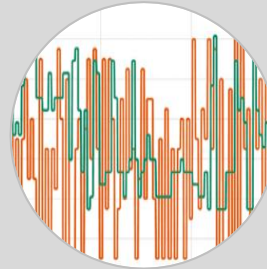
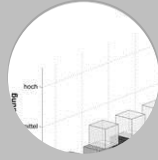
Determination of the Load on all components to be considered:

- Systematic Analysis of Customer Usage
- Algorithm for Detection of all Customer Types
- Derivation of representative Load Spectra for each Component by Using Damage Accumulation Hypothesis

Method „Road2Dyno“

Step 2 - Determination of representative Load Spectra





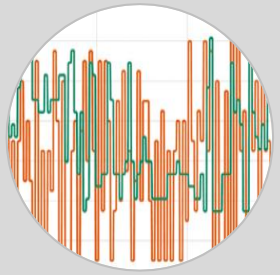
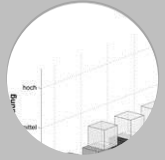
Determination of Testing Profiles with the SDC-Tool – Synthetic Driving Cycle - Tool:

Consideration of the following Parameters:

- Vehicle Speed
- current vehicle longitudinal acceleration
- following Vehicle longitudinal acceleration
- Operational Profile
- Driving Style
- Vehicle Condition
- Vehicle lateral acceleration
- Stop Duration
- etc.

Method „Road2Dyno“

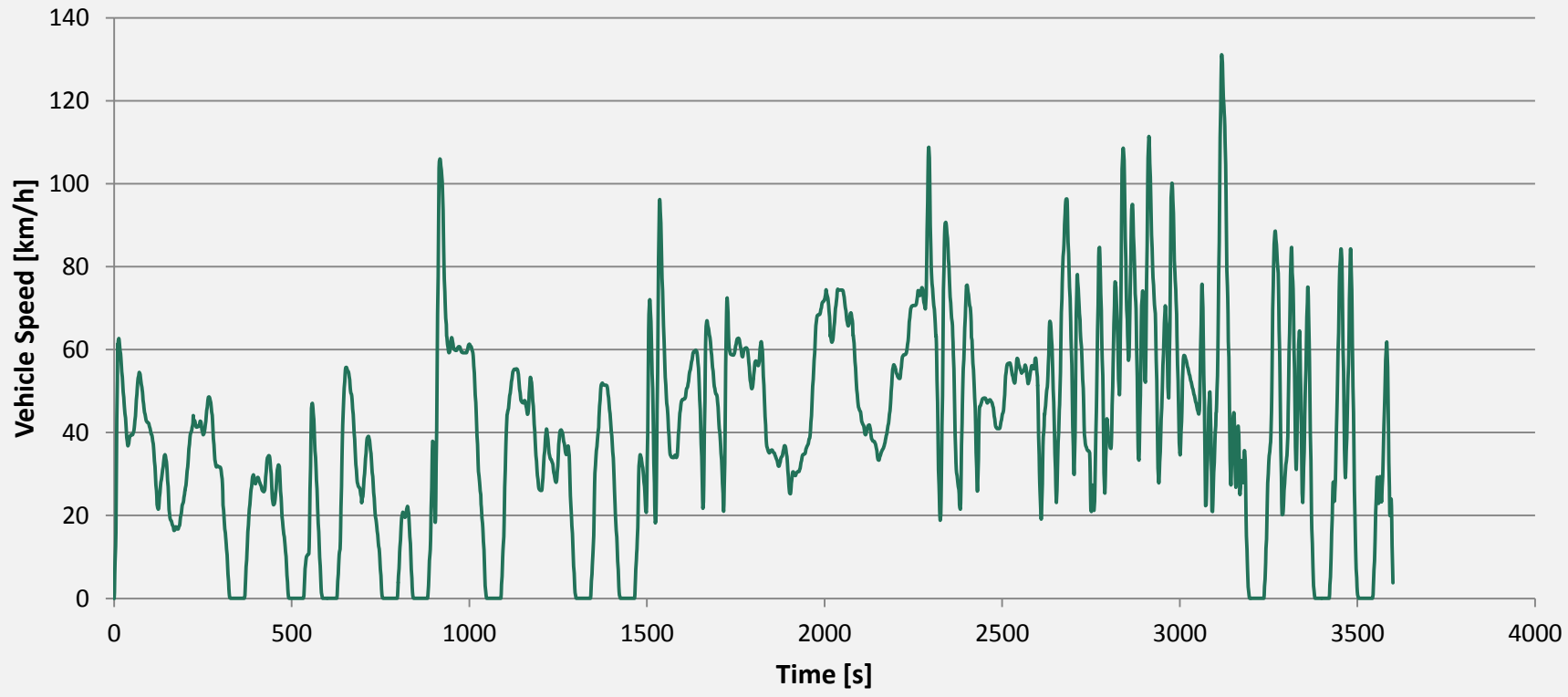
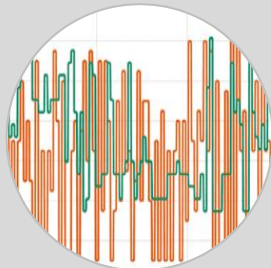
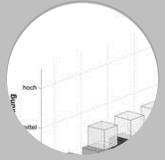
Step 3 - Derivation of Testing Profiles

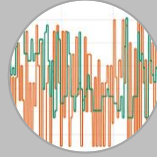
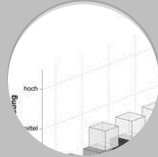


Time [s]	Vehicle Speed [km/h]	Operational Profile	Driving Style	Vehicle Condition	longitudinal acceleration [m/s ²]	foIII. longitudinal acceleration [m/s ²]	Max. Vehicle Speed [km/h]	Selection Criterion
0	0	3	3	1	0	0	300	0
1	::	::	::	::	::	::	::	::
2	::	::	::	::	::	::	::	::

Method „Road2Dyno“

Step 3 - Derivation of Testing Profiles





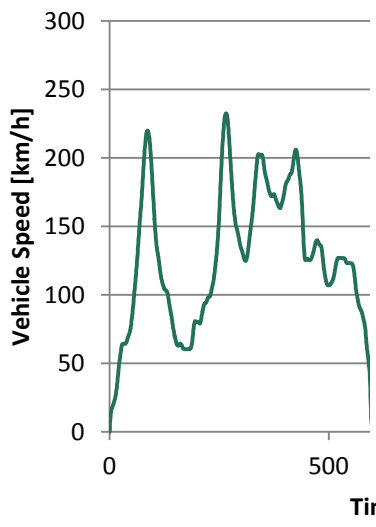
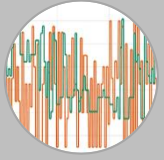
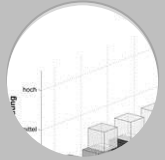
Integration of Acceleration Factors:

Generating virtual Load Spectra from synthetic Driving Cycles:

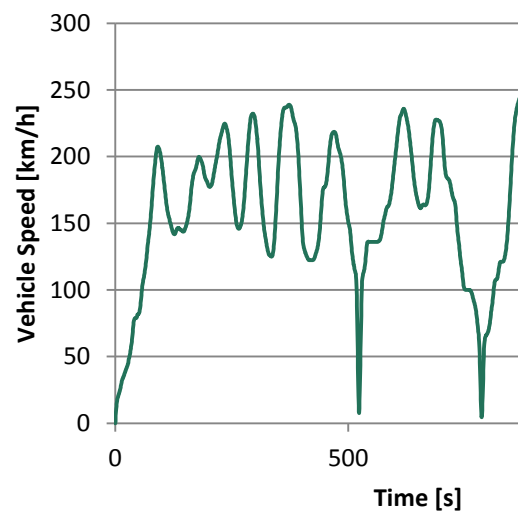
- Usage of a Full Vehicle Simulation Environment => IPG Carmaker
- Installation and Validation of a Vehicle and Driver Modell
- Alternative Usage: Parameter Variation for Effects Analysis on Real Driving Load Spectra
 - Powertrain Parameters
 - Engine Parameters
 - Degree of Electrification
 - Driving Style
 - Operational Profile
 - Vehicle Condition

Method „Road2Dyno“

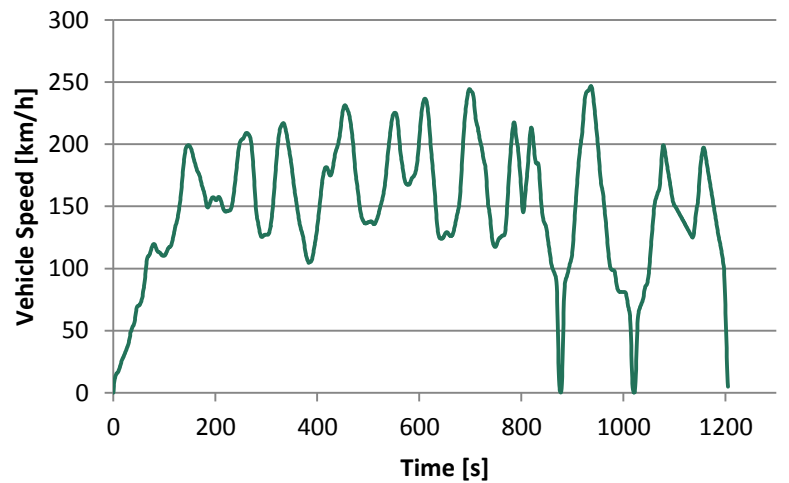
Step 4 - Integration of Acceleration Factors



Damage Mechanism 1



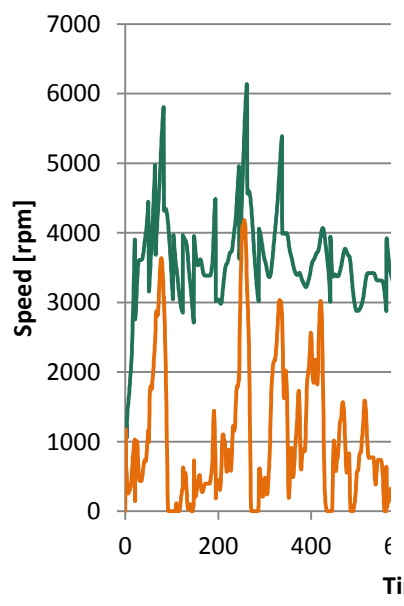
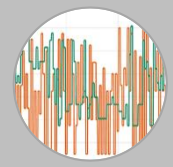
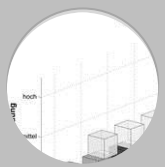
Damage Mechanism 2



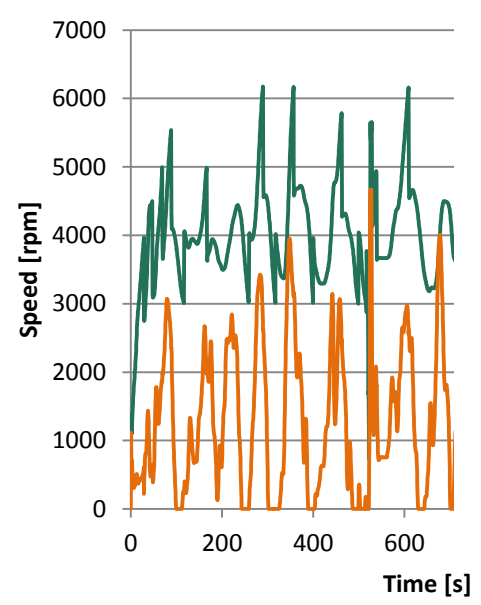
Damage Mechanism 3

Method „Road2Dyno“

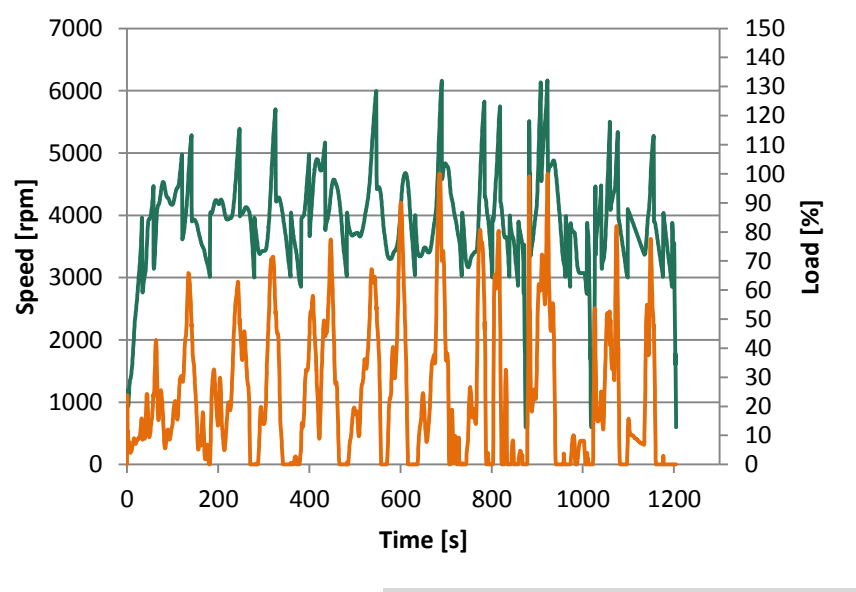
Step 4 - Integration of Acceleration Factors



Damage Mechanism 1



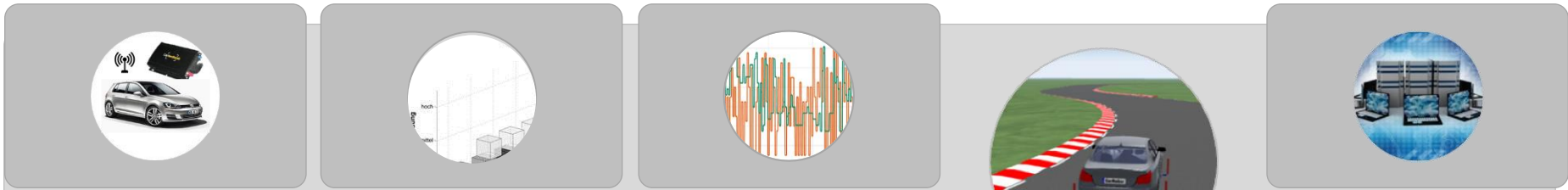
Damage Mechanism 2



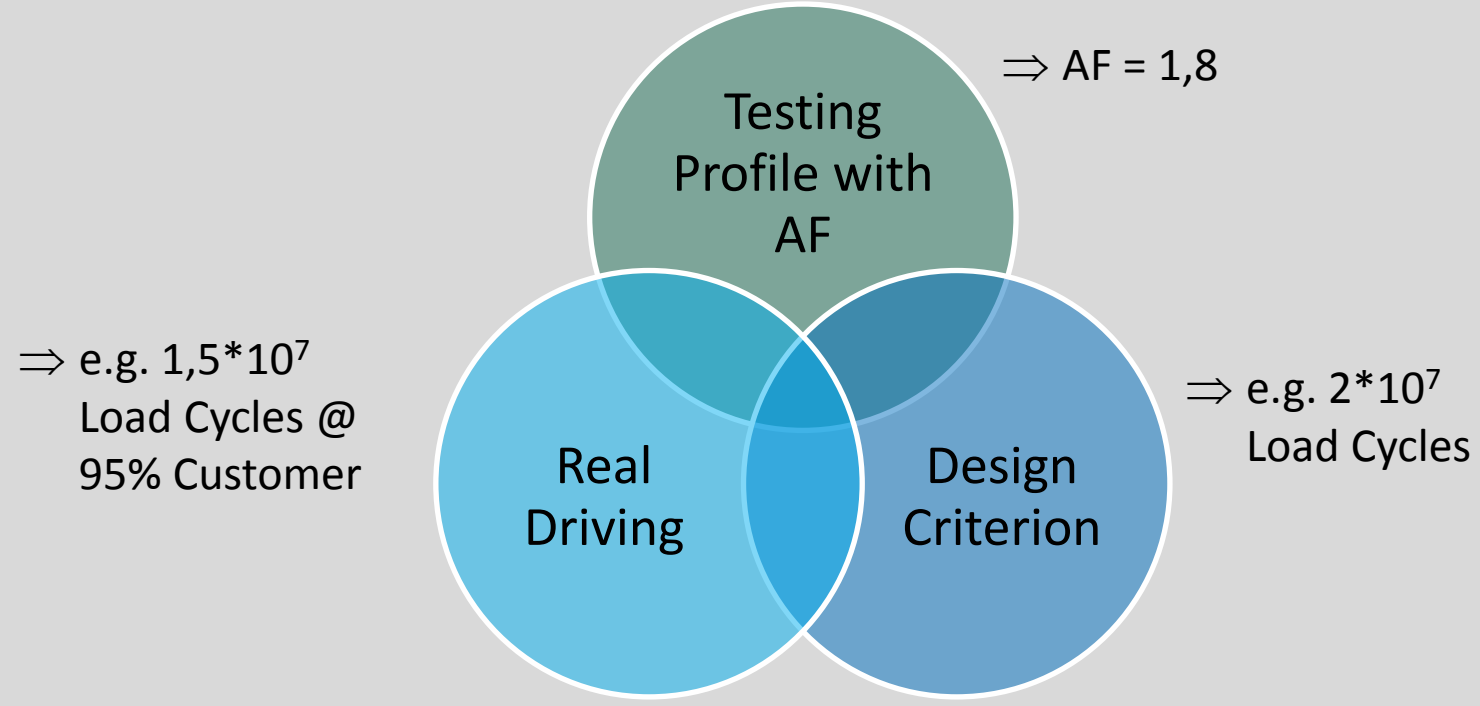
Damage Mechanism 3

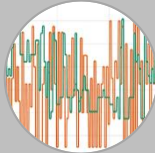
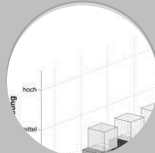
Method „Road2Dyno“

Step 4 - Integration of Acceleration Factors

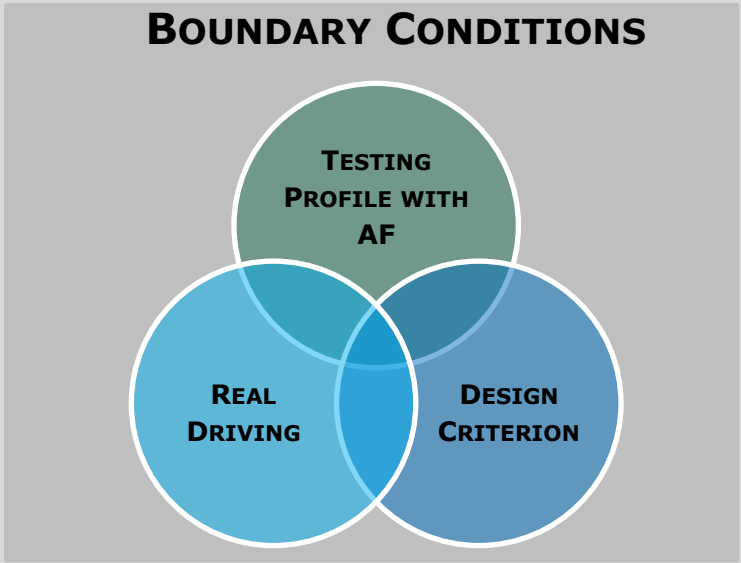
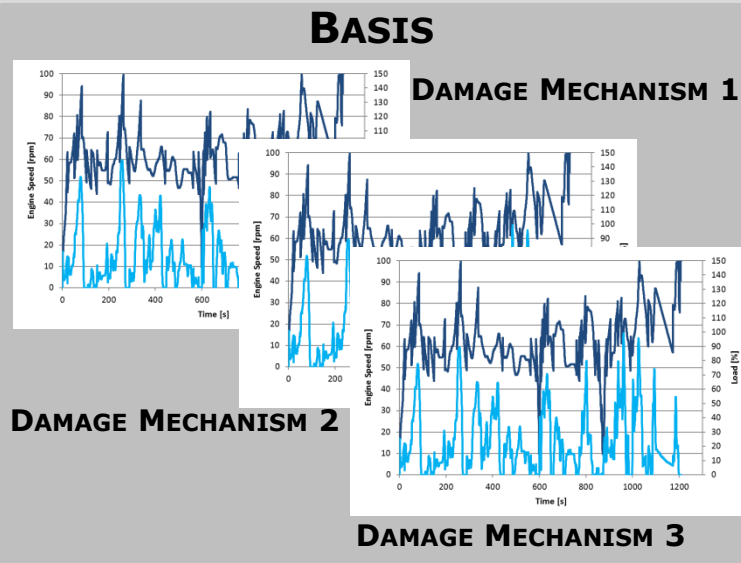


Derivation of the precise test specification using the following criteria:

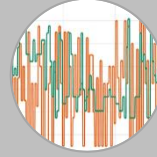
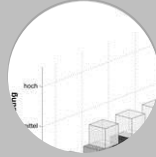




GENETEC – GENERATOR FOR ENDURANCE TESTING CYCLES



CONVENTIONAL TESTING PROFILE: 300 H
NEW TESTING PROFILE: 210 H → **TIME SAVING OF 30 %**



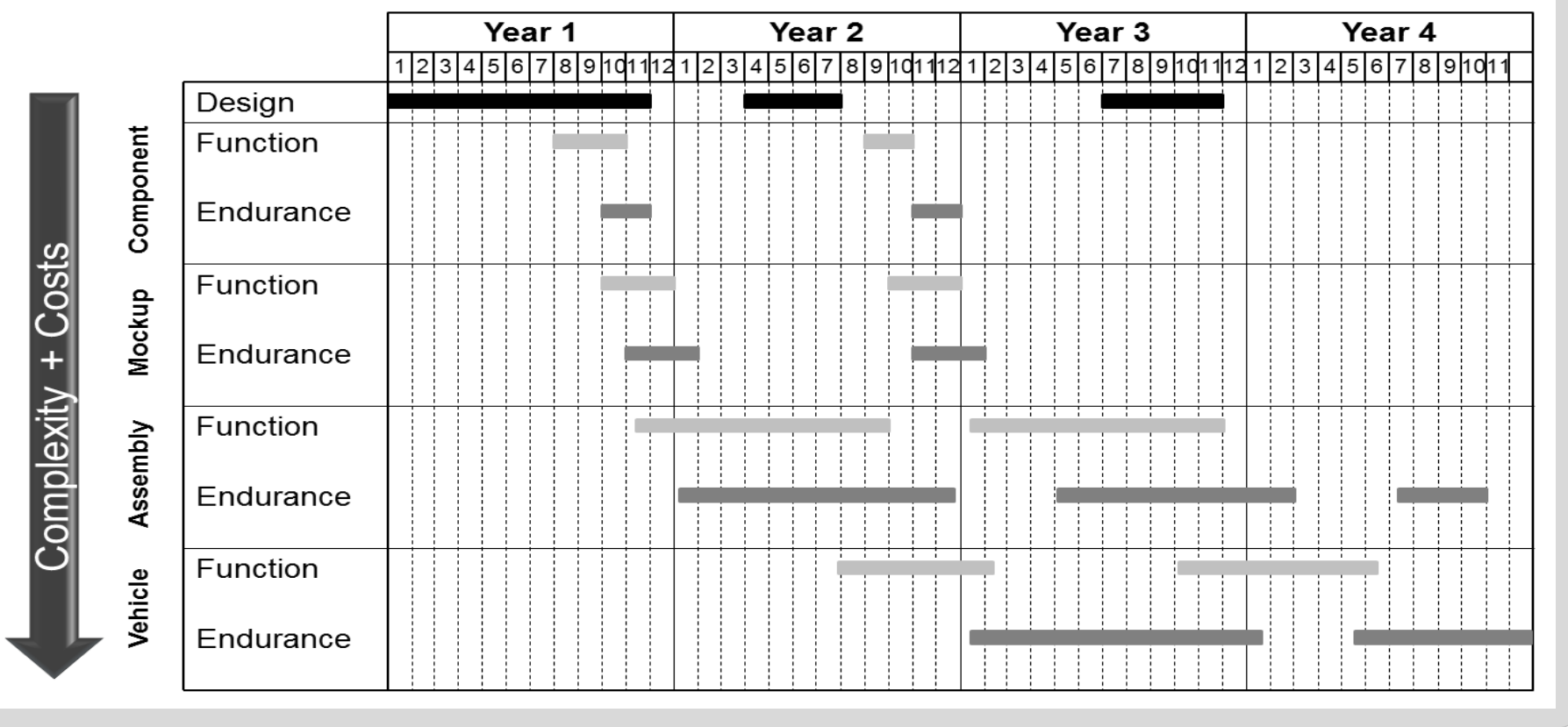
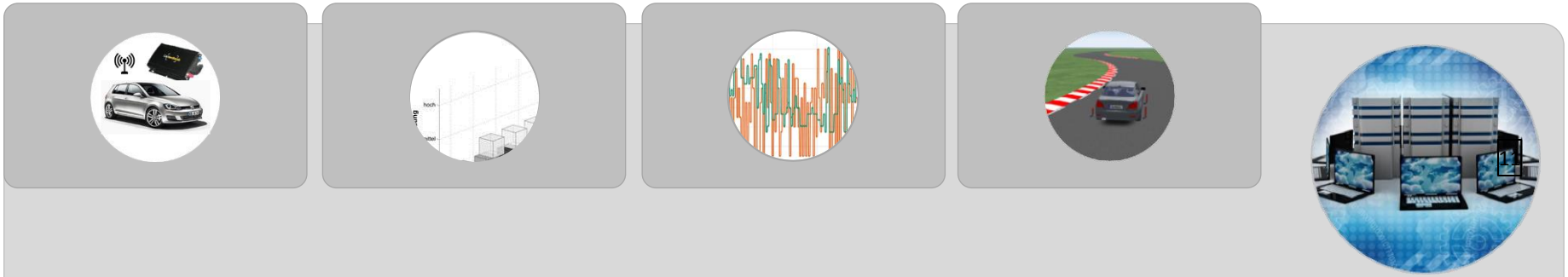
Database Management:

Utilization of enquired Real Driving Data:

- Integration of Real Driving Load Spectra in a Holistic Development Process
- Detailed automated Evaluation and Conjunction Algorithms as Basis for Component Design
- Access for all Development Engineers
- Transfer of enquired Driving Style and Customer Driving Behaviour Data to Future Vehicle Concepts

Method „Road2Dyno“

Step 5 – Database Management



- Motivation
- Transfer of the „Road2Dyno“-Method to Electrified Powertrains
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- Presentation of a methodology for the integration of customer representative load spectra into the testing process by generating well-defined as well as time- and thus cost-optimal testing profiles
- Indication of the reduction potential with regard to test time and test costs
- Implementation of the methodology even in the early stages of the development process promises reliable information about system robustness concerning performance, emission behaviour or reliability
- Ensuring customer-usage-related conditions by performing reproducible testing procedures for comparison of different component suppliers, development stages or product layouts



Vielen Dank !